

APPROVED O.G. FIG.
CLASS SUBCLASS
BY
DRAFTSMAN

Title: METHOD OF DETERMINING MOVEMENT
SEQUENCE, ALIGNMENT APPARATUS, METHOD
AND APPARATUS OF DESIGNING OPTICAL
SYSTEM, AND MEDIUM IN WHICH PROGRAM
REALIZING THE DESIGNING METHOD

Inventor(s): Koji YOSHIDA, et al
DOCKET NO.: 061807-0137

Fig. 1

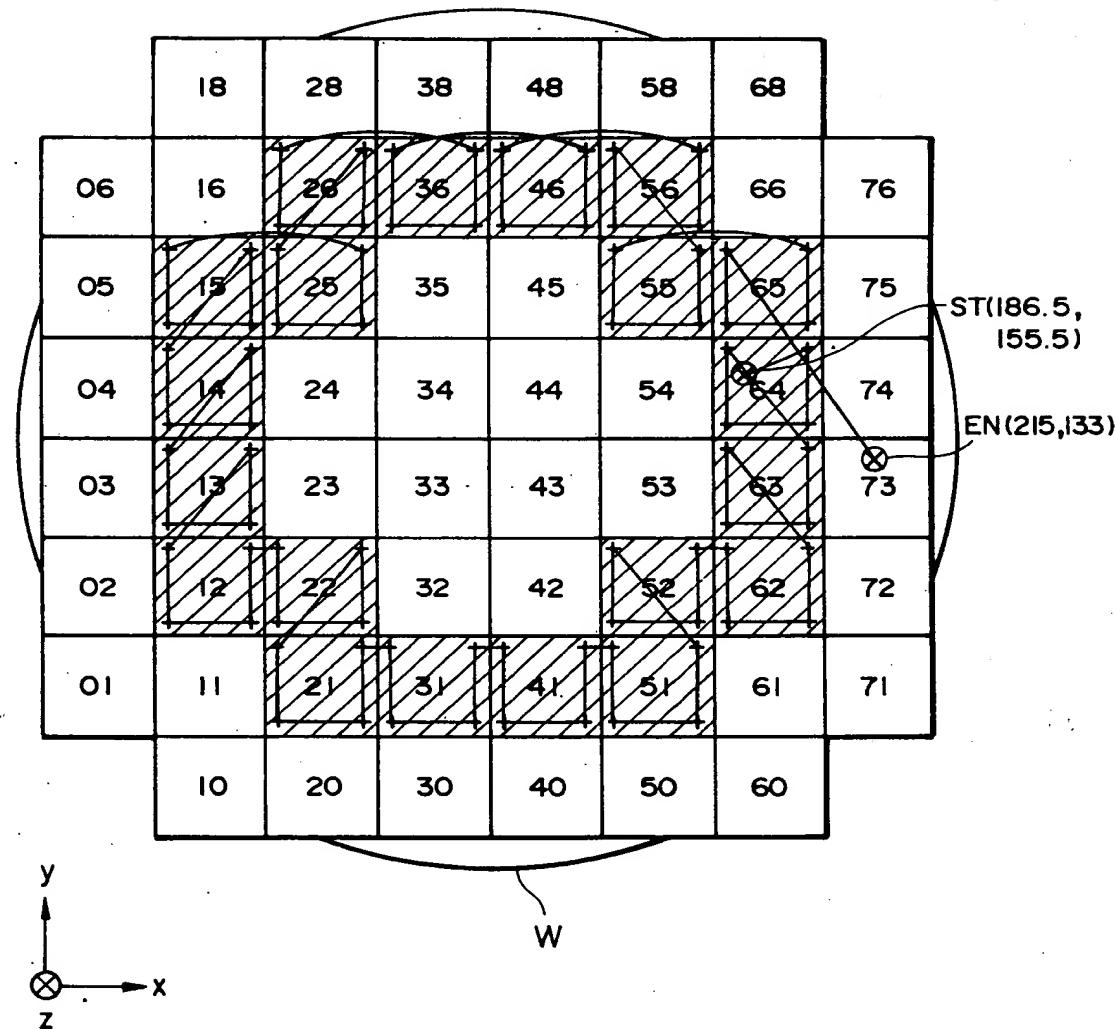
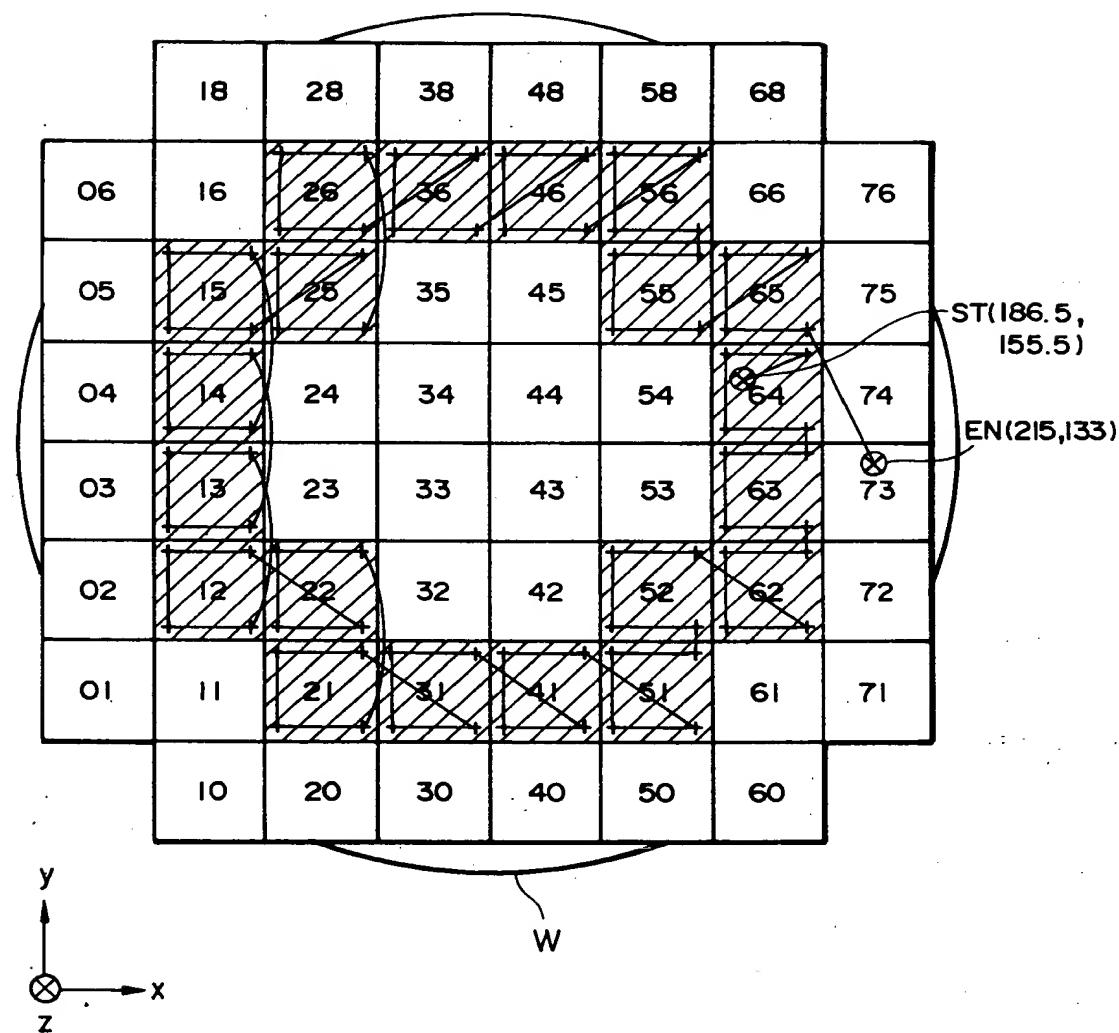


Fig. 2



Crossover point

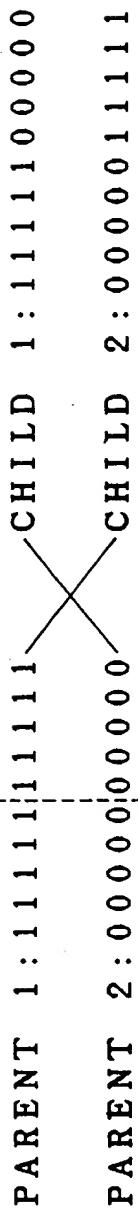


Fig.3

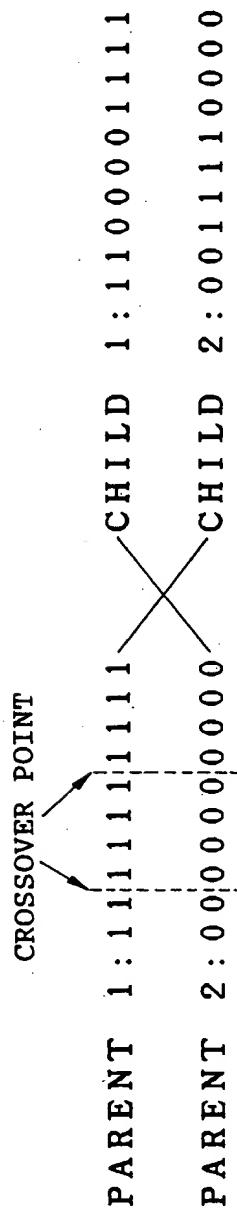


Fig.4

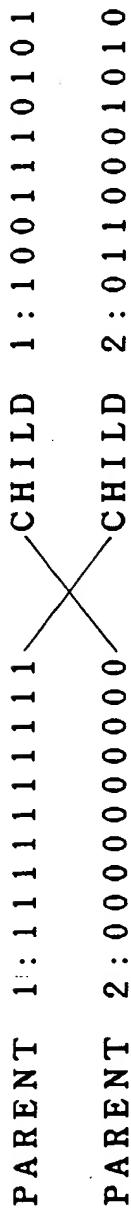


Fig.5

Fig. 6

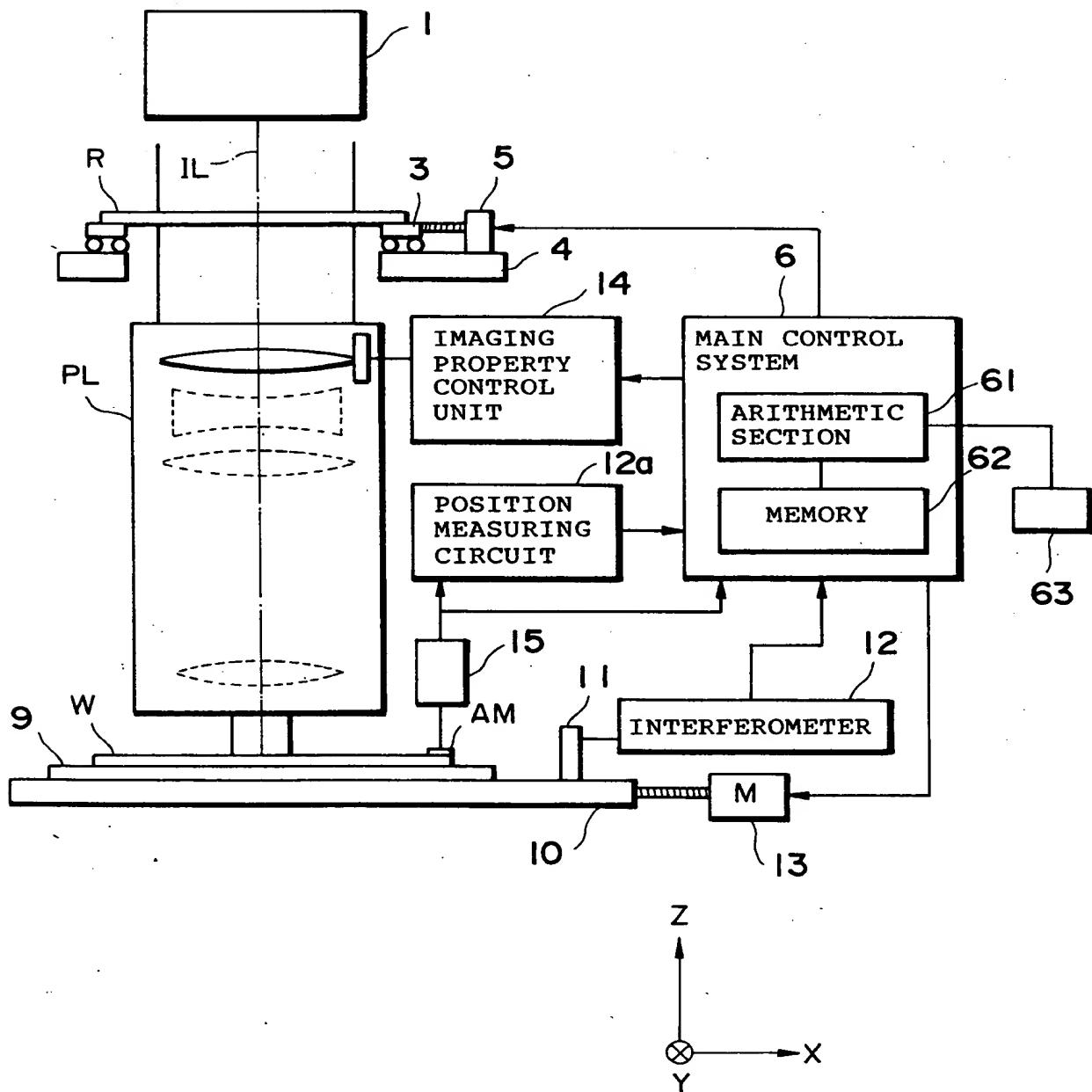


Fig. 7

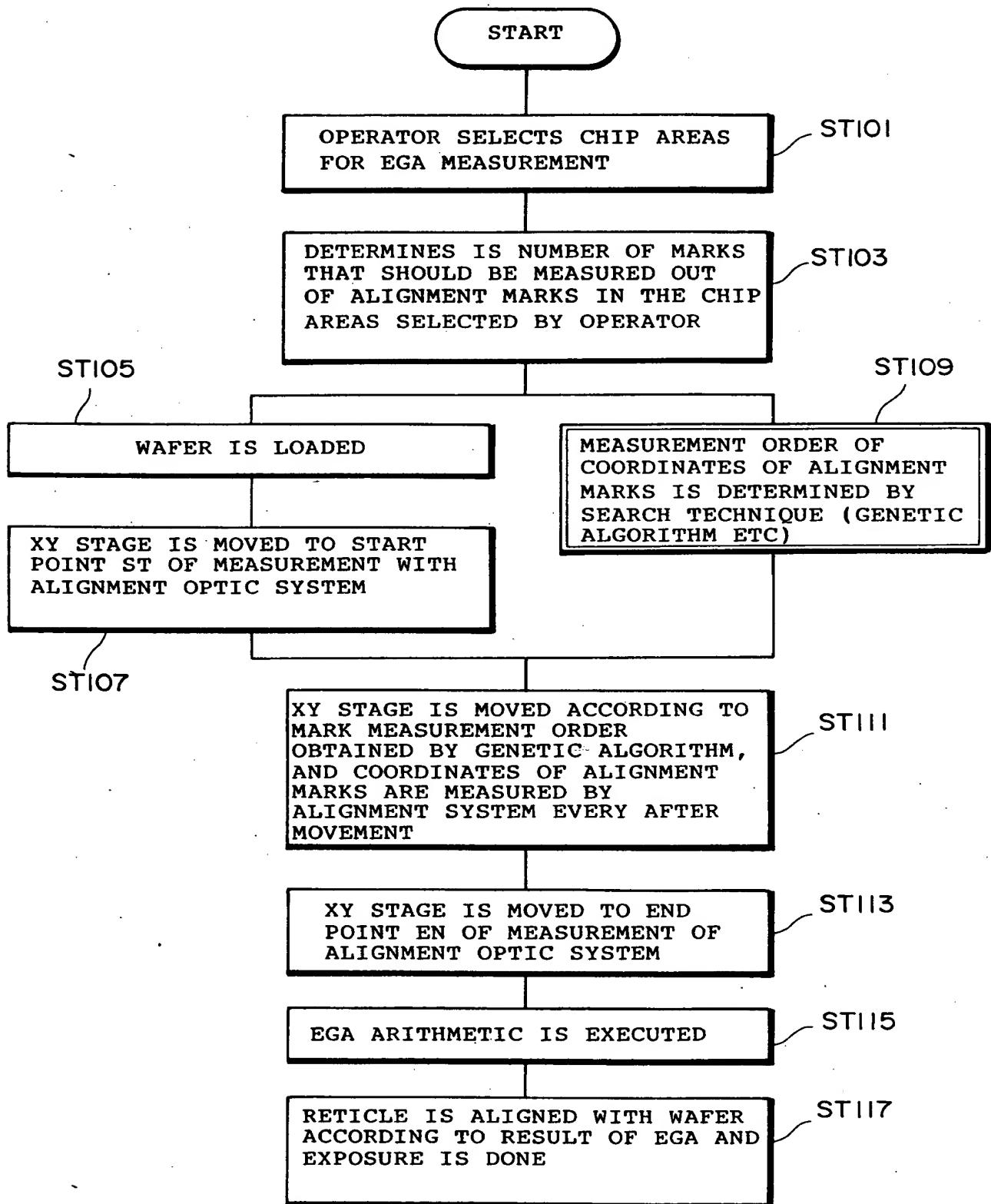


Fig.8

ATTRIBUTE	VALUE OF PARAMETER SET IN EMBODIMENT	
START POINT ST	X	186.5 (mm)
	Y	155.5 (mm)
END POINT EN	X	215 (mm)
	Y	133 (mm)
ACCELERATION OF WAFER STAGE 10	X	0.34 g
	Y	0.2 g
MAX SPEED OF WAFER STAGE 10	X	270 (mm/sec)
	Y	200 (mm/sec)
SETTLING TIME OF WAFER STAGE		0.032 (sec)
TIME NECESSARY FOR MEASURING COORDINATES OF ONE ALIGNMENT MARK		0.5 (sec)

g:ACCELERATION OF GRAVITY (=9.80m/sec)

Fig.9

CHIP AREA	COORDINATES OF CENTER	CHIP AREA	COORDINATES OF CENTER
12	(83, 105)	41	(149, 83)
13	(83, 127)	46	(149, 193)
14	(83, 149)	51	(171, 83)
15	(83, 171)	52	(171, 105)
21	(105, 83)	55	(171, 171)
22	(105, 105)	56	(171, 193)
25	(105, 171)	62	(193, 105)
26	(105, 193)	63	(193, 127)
31	(127, 83)	64	(193, 149)
36	(127, 193)	65	(193, 171)

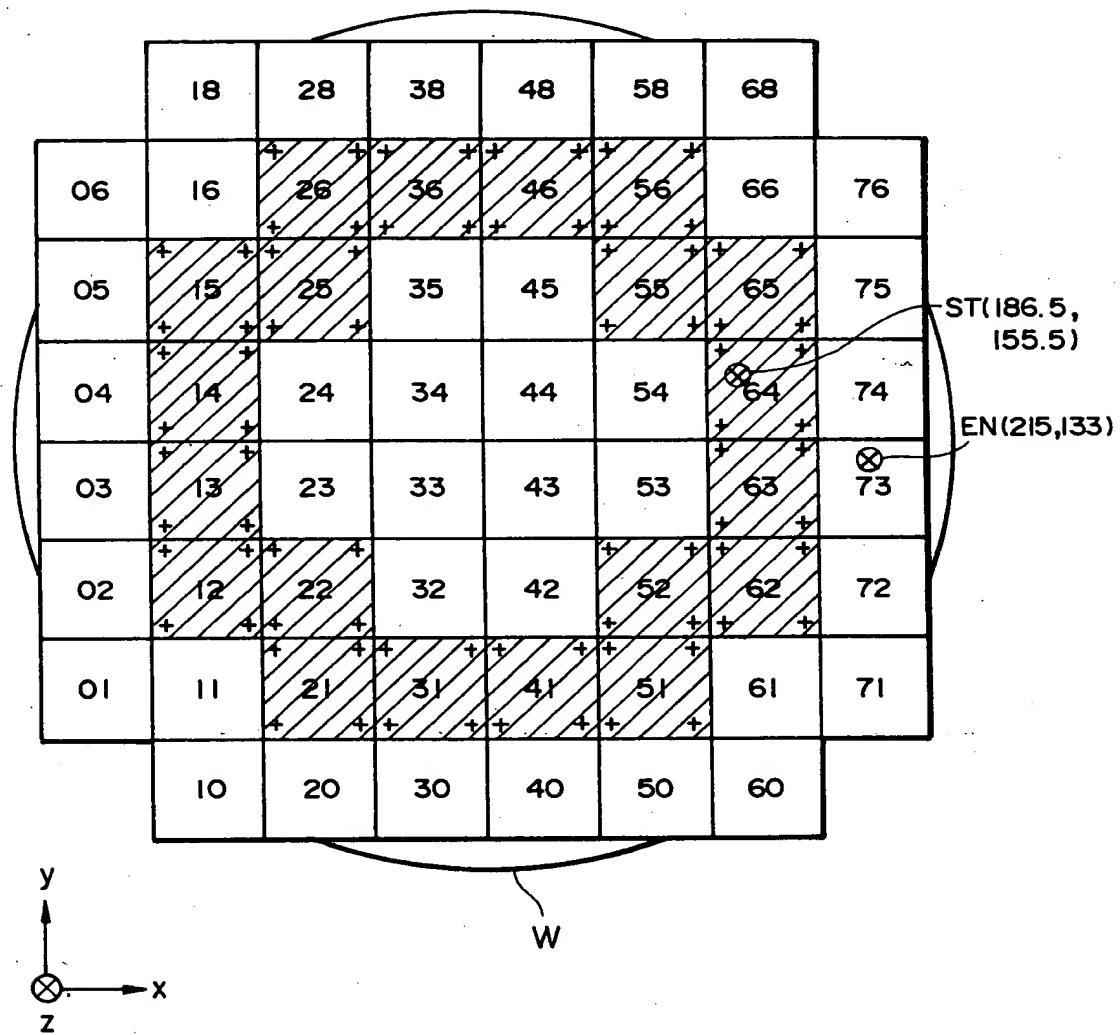
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	START	12(1)	12(2)	12(3)	12(4)	13(1)	13(2)	
12(1)	0.378296	X	0.109449	0.132981	0.132981	0.142	0.142	
12(2)	0.45237	0.109449	X	0.132981	0.132981	0.142	0.142	
12(3)	0.45237	0.132981	0.132981	X	0.109449	0.242	0.242	
12(4)	0.378296	0.132981	0.132981	0.109449	X	0.242	0.242	
13(1)	0.378296	0.142	0.142	0.242	X	0.109449	0.109449	
13(2)	0.45237	0.142	0.142	0.242	0.242	0.109449	X	
...	
64(3)	0.123721	0.36533	0.439407	0.439407	0.36533	0.36533	0.439407	
64(4)	0.123721	0.439407	0.513481	0.513481	0.439407	0.439407	0.513481	
65(1)	0.1595	0.439407	0.513481	X	0.513481	0.462	0.439407	0.513481
65(2)	0.1595	0.36533	0.439407	0.462	0.462	0.36533	0.439407	
65(3)	0.084955	0.36533	0.439407	0.439407	0.36533	0.36533	0.439407	
65(4)	0.102346	0.439407	0.513481	0.513481	0.439407	0.439407	0.513481	
END	X	0.483852	0.557926	0.557926	0.483852	0.483852	0.557926	
...	
								F
								(UNIT: SEC)

Fig. 10

Fig. 11



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Fig. 12

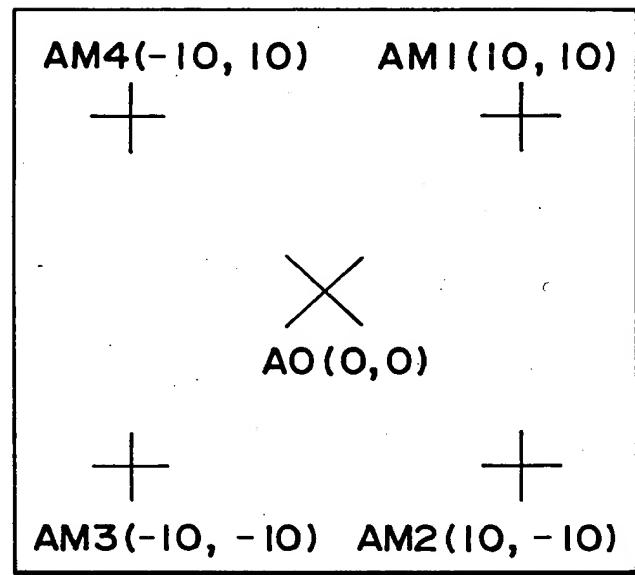
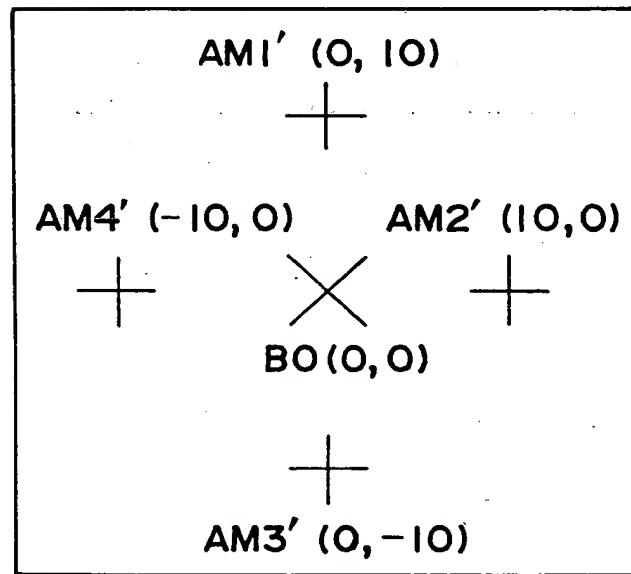


Fig. 13



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Fig. 14

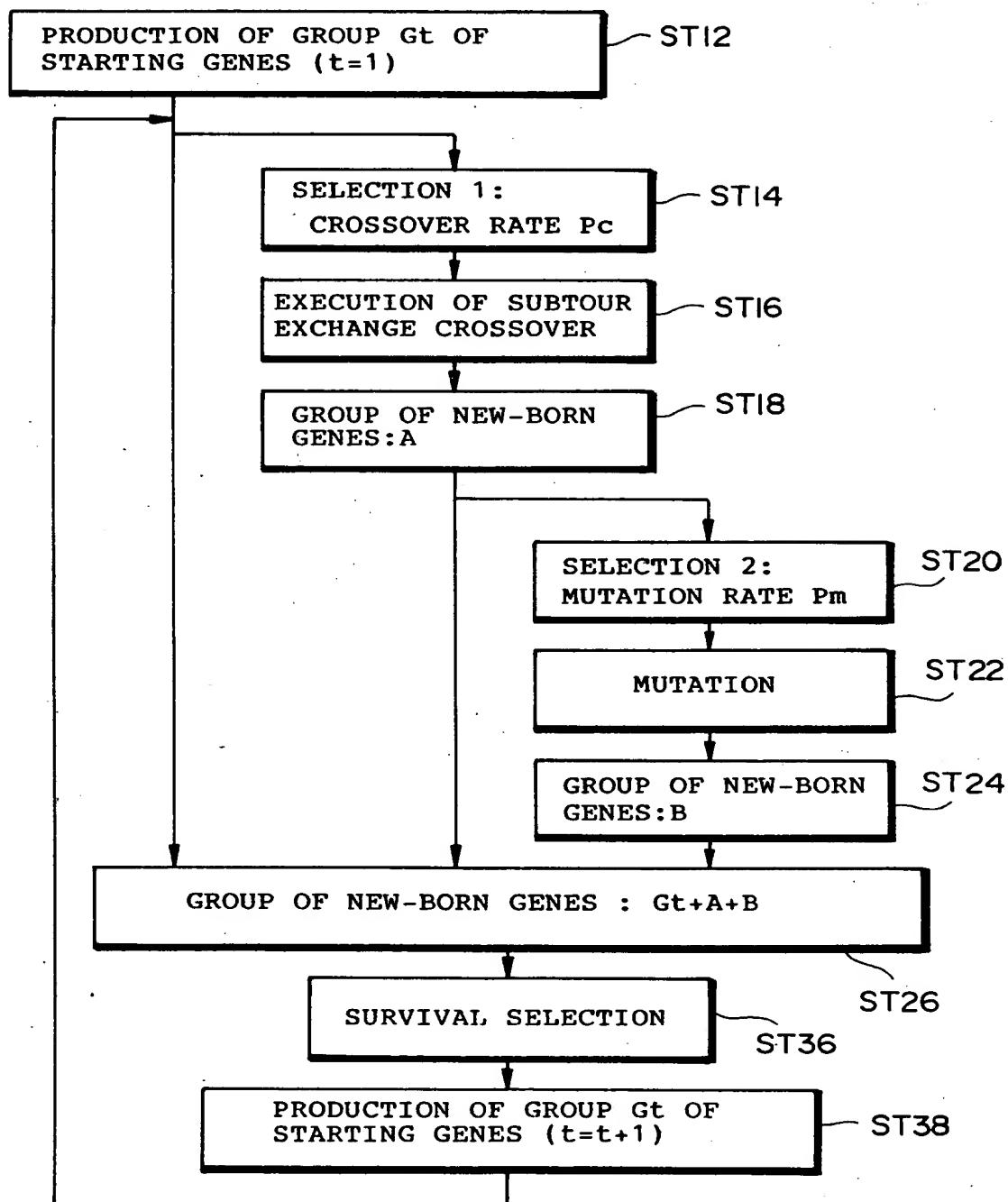


Fig. 15

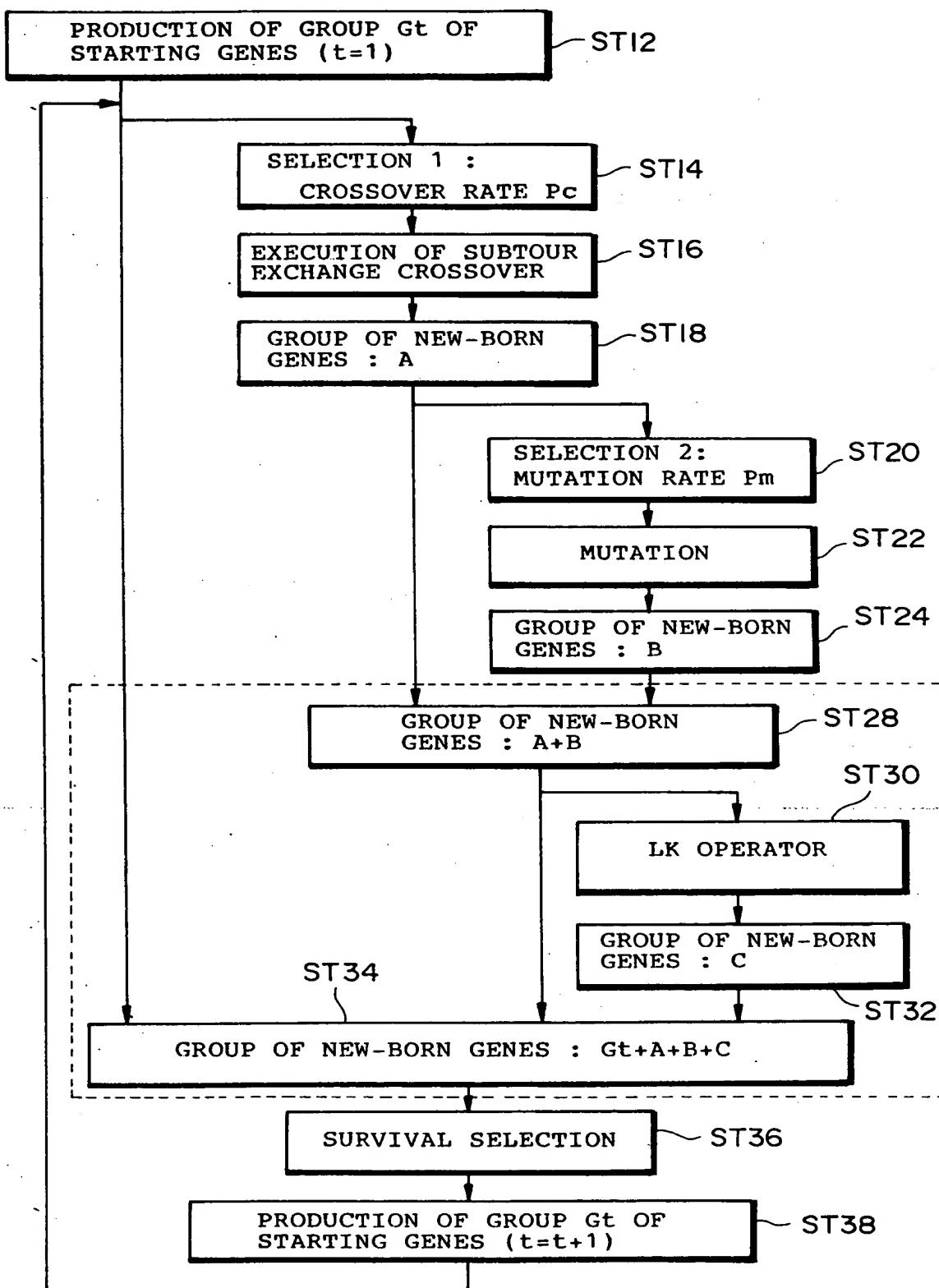


Fig. 16

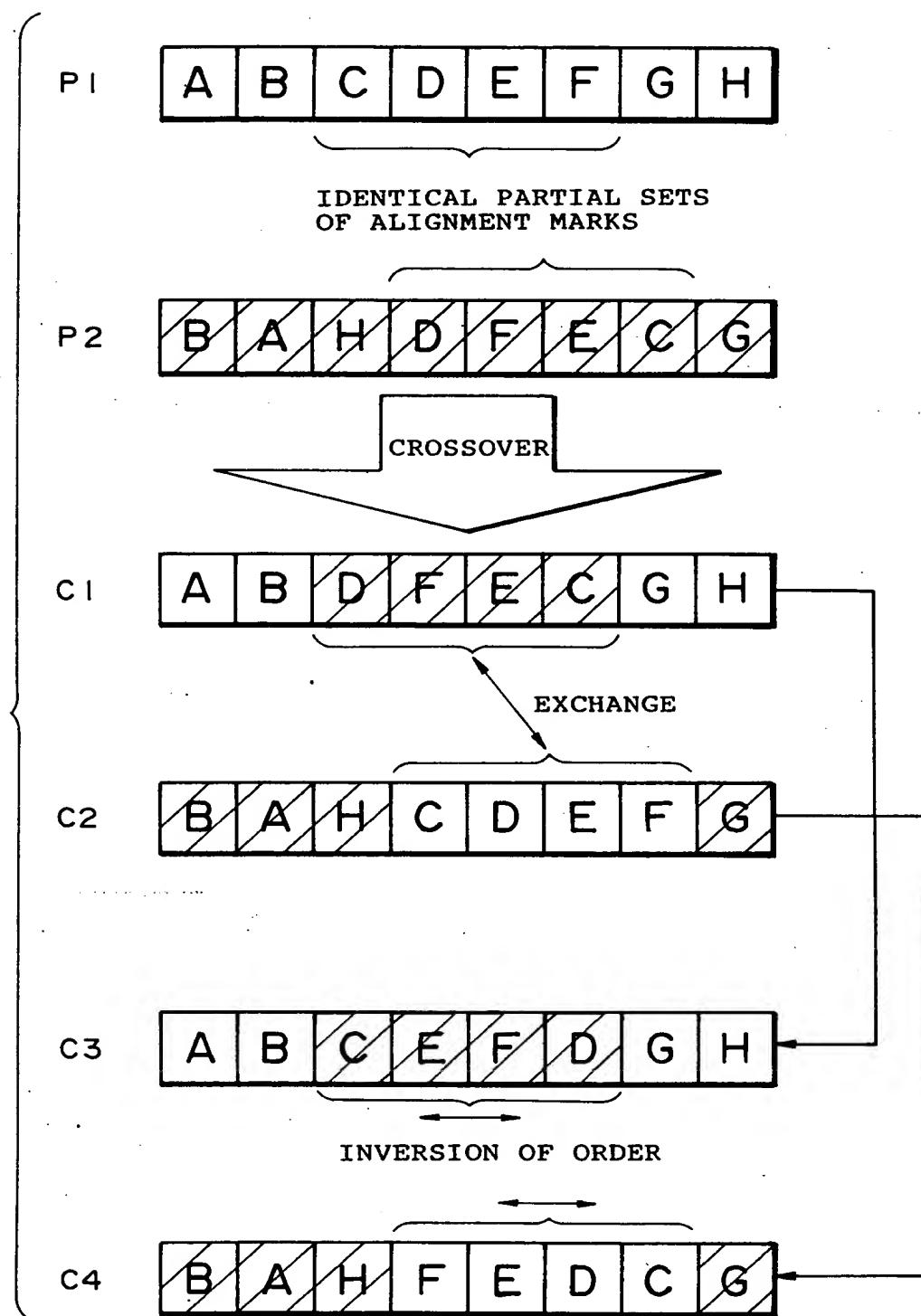


Fig. 17

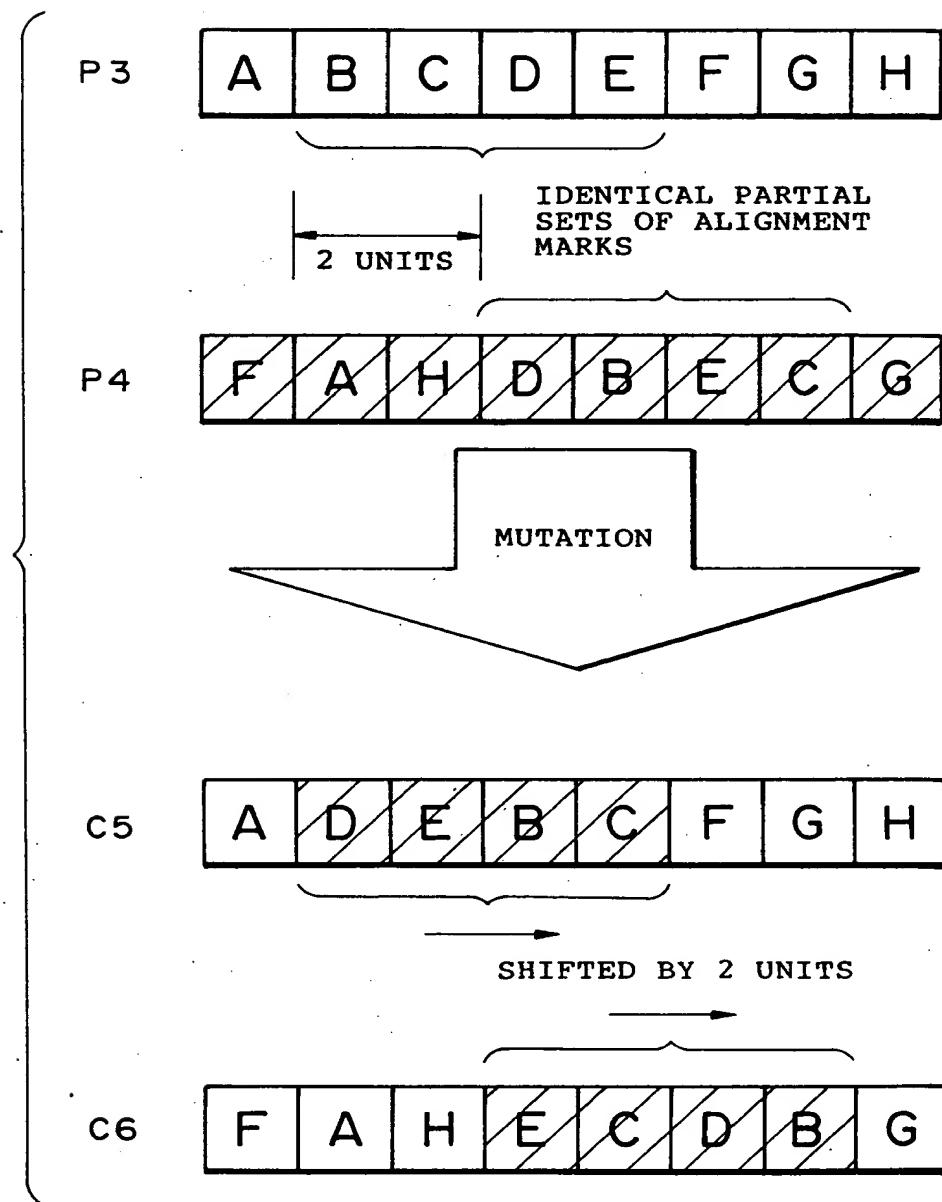


Fig. 18

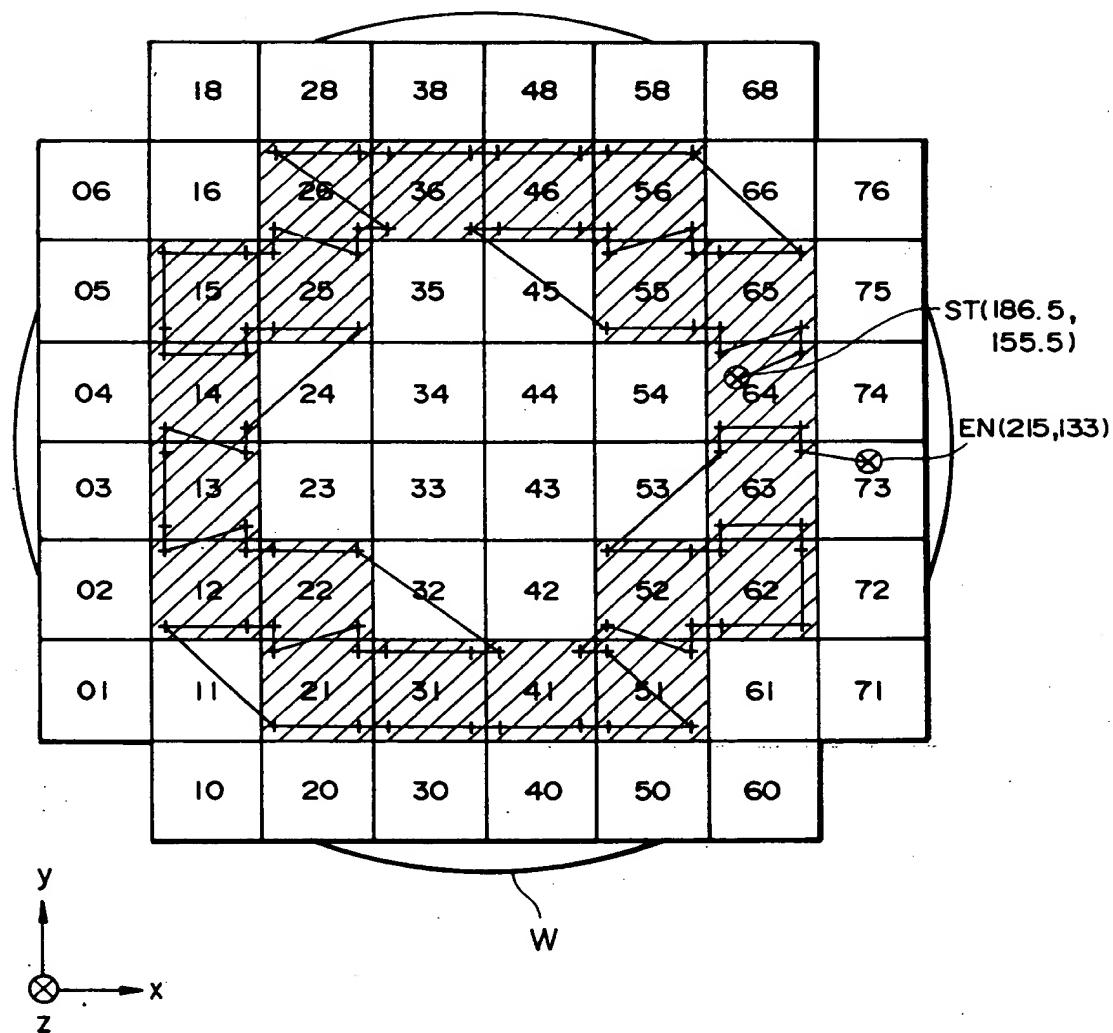
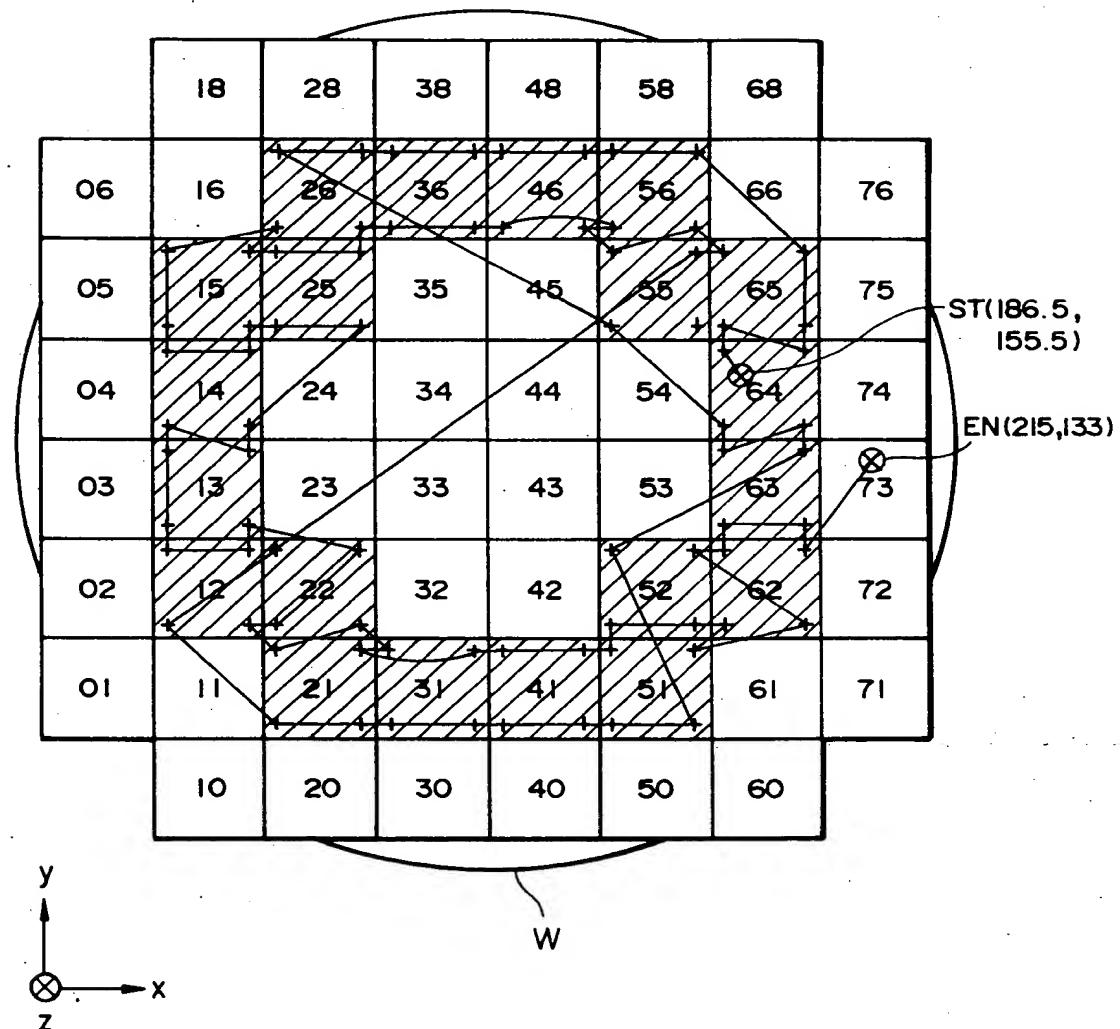


Fig. 19



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Fig.20

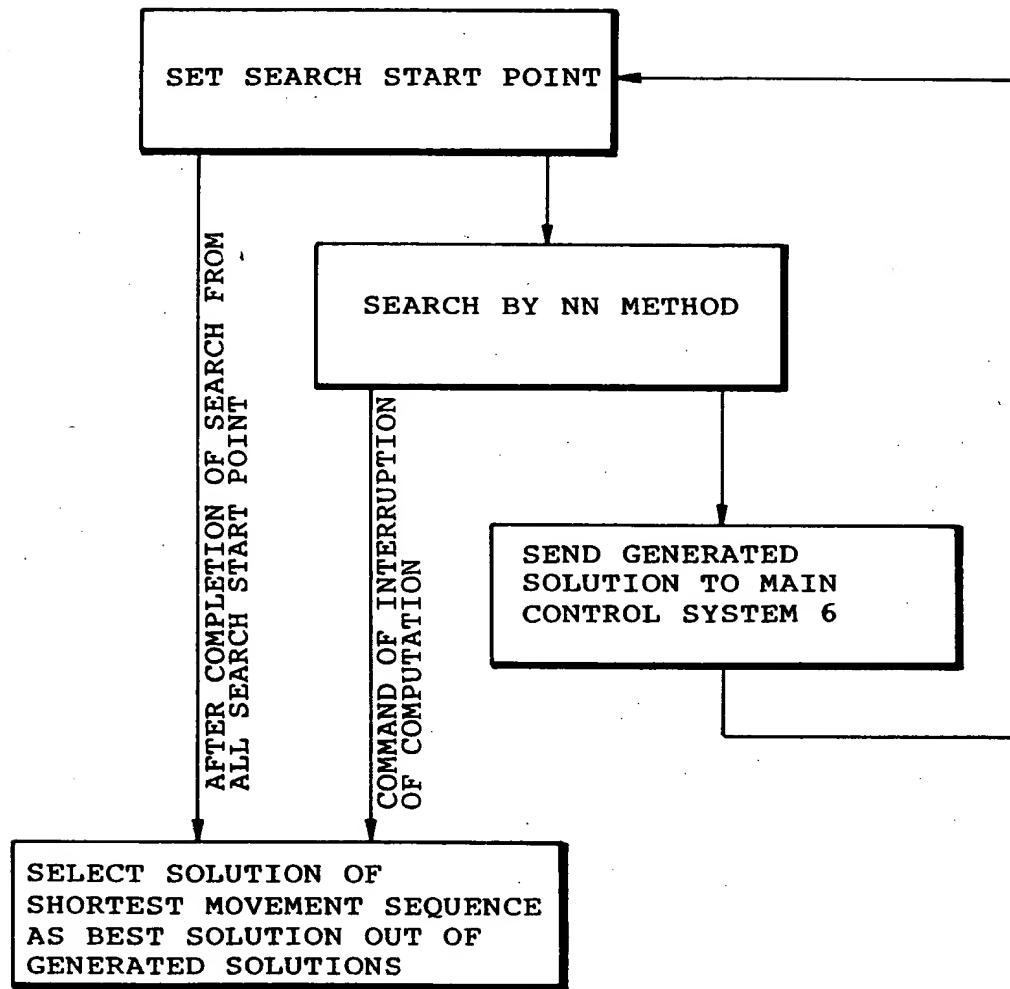


Fig. 21

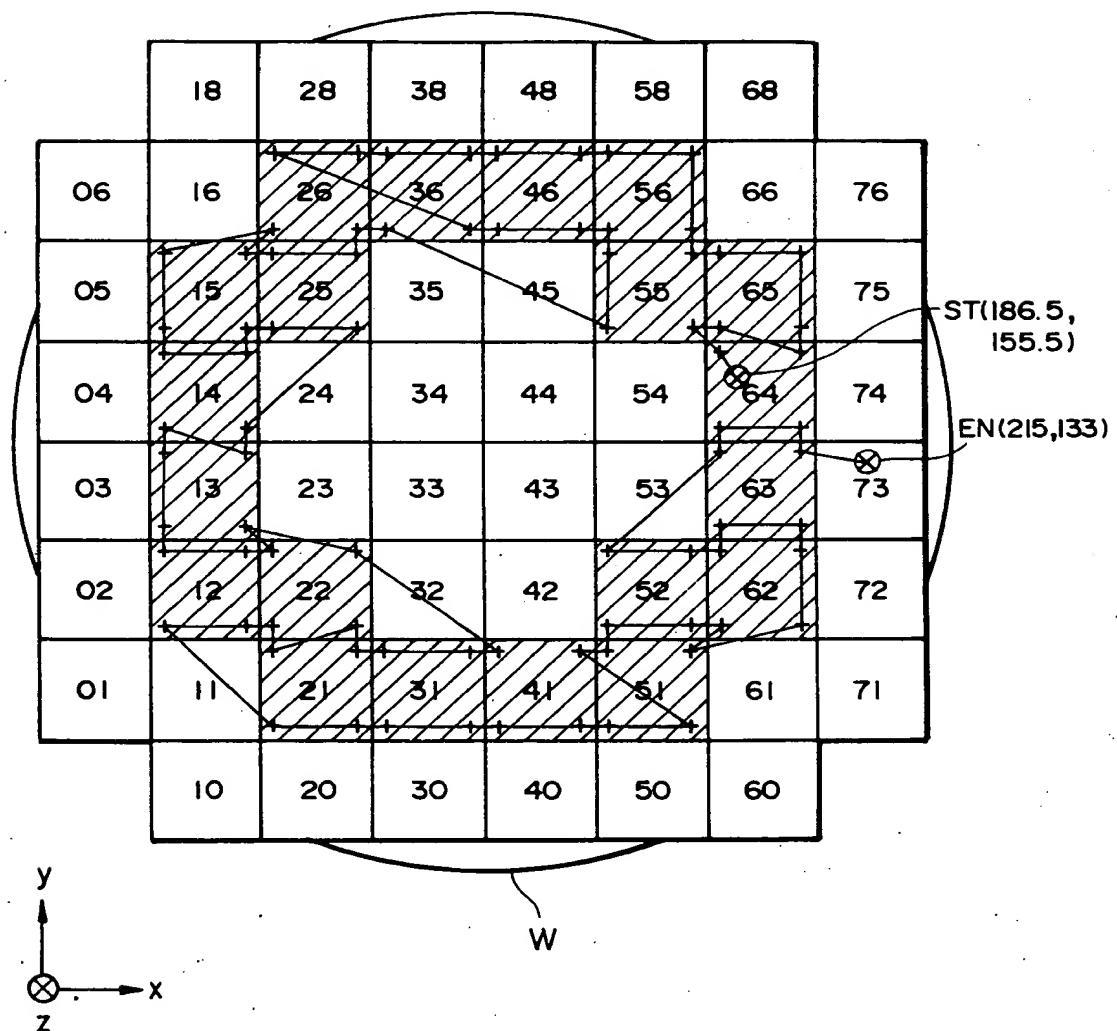
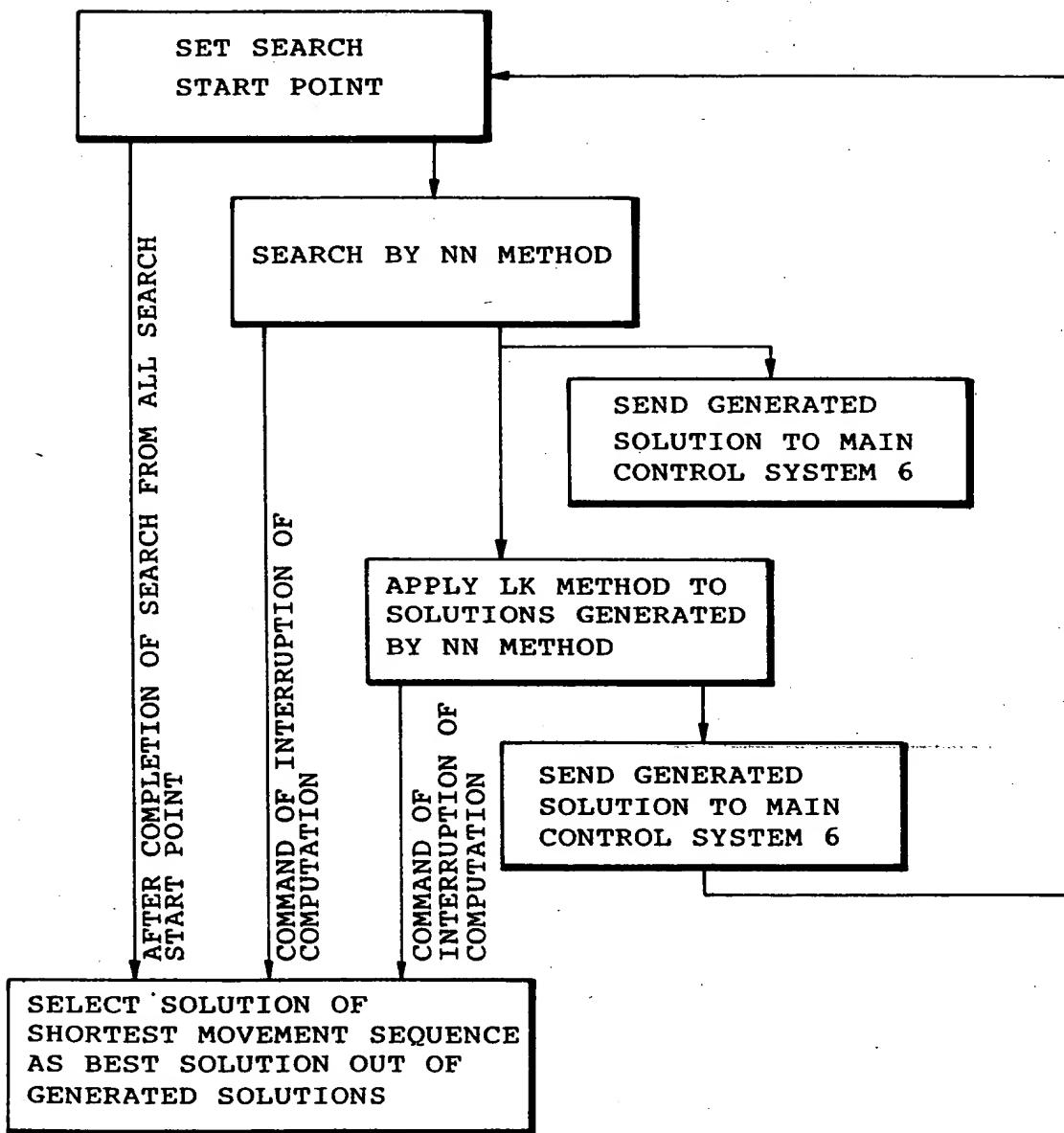


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DOCKET NO.: 061807-0137

DOCKET NO.: 061807-0137

OVERALL MOVEMENT TIME OF MOVEMENT SEQUENCE AS BEING SOLUTION GAINED BY APPROACH BASED ON RULE OF THUMB

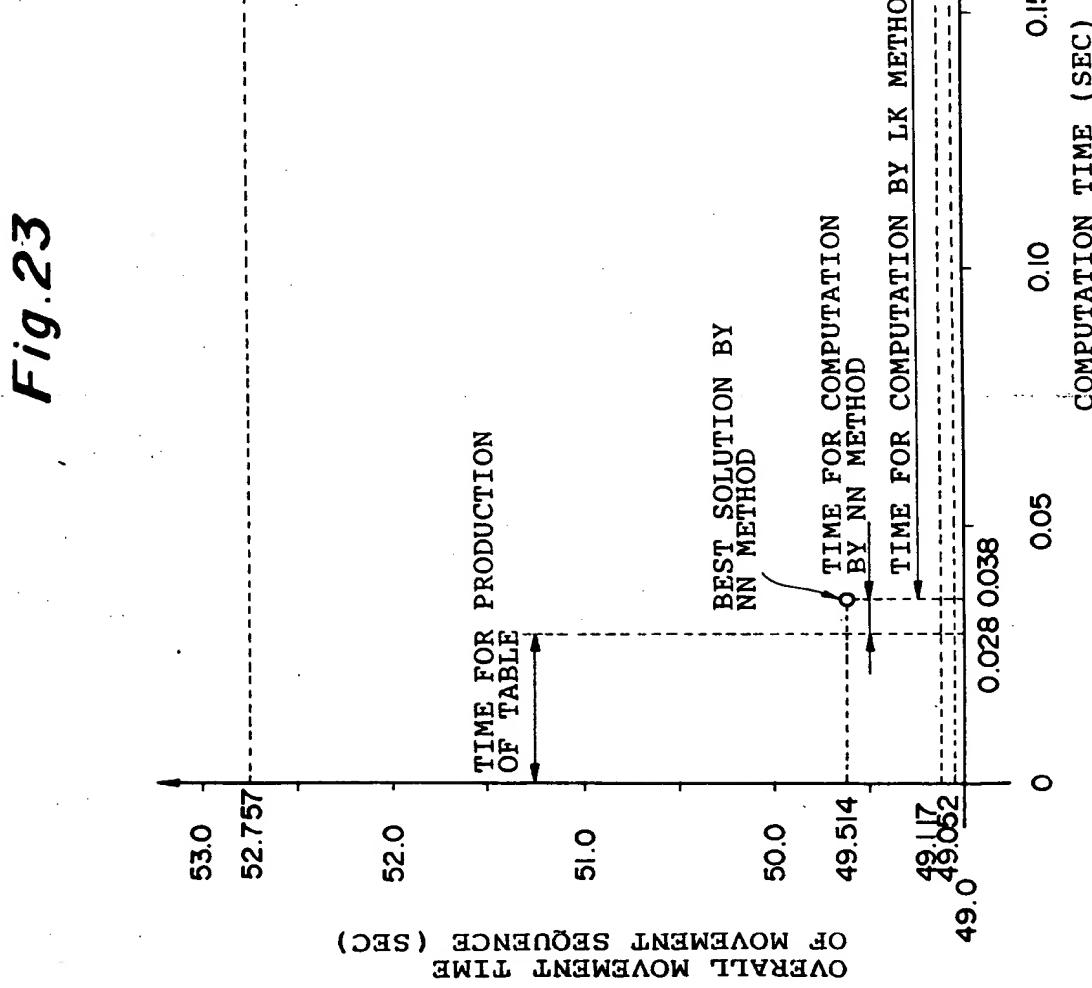
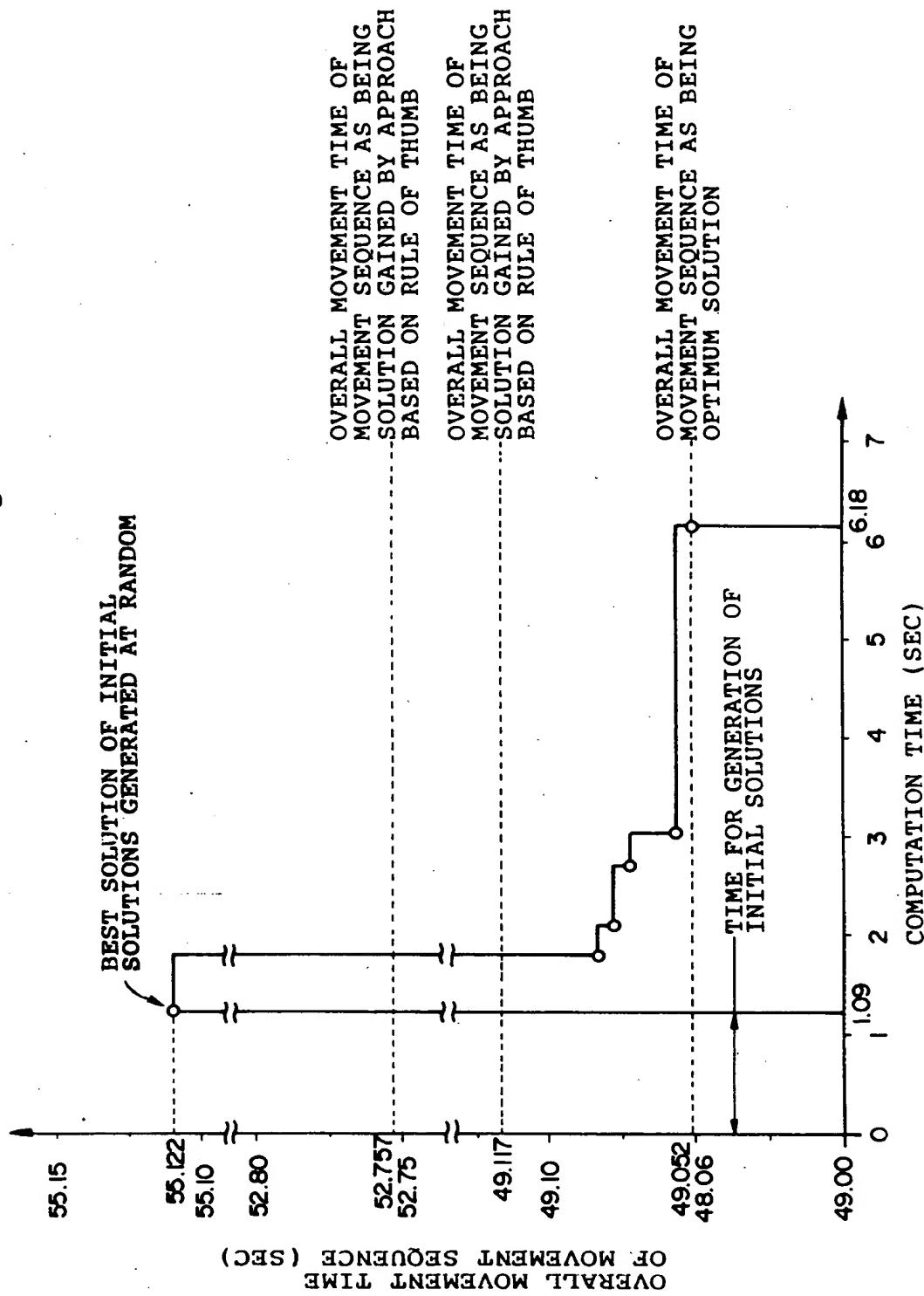


Fig. 24



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DOCKET NO.: 061807-0137

Fig. 25

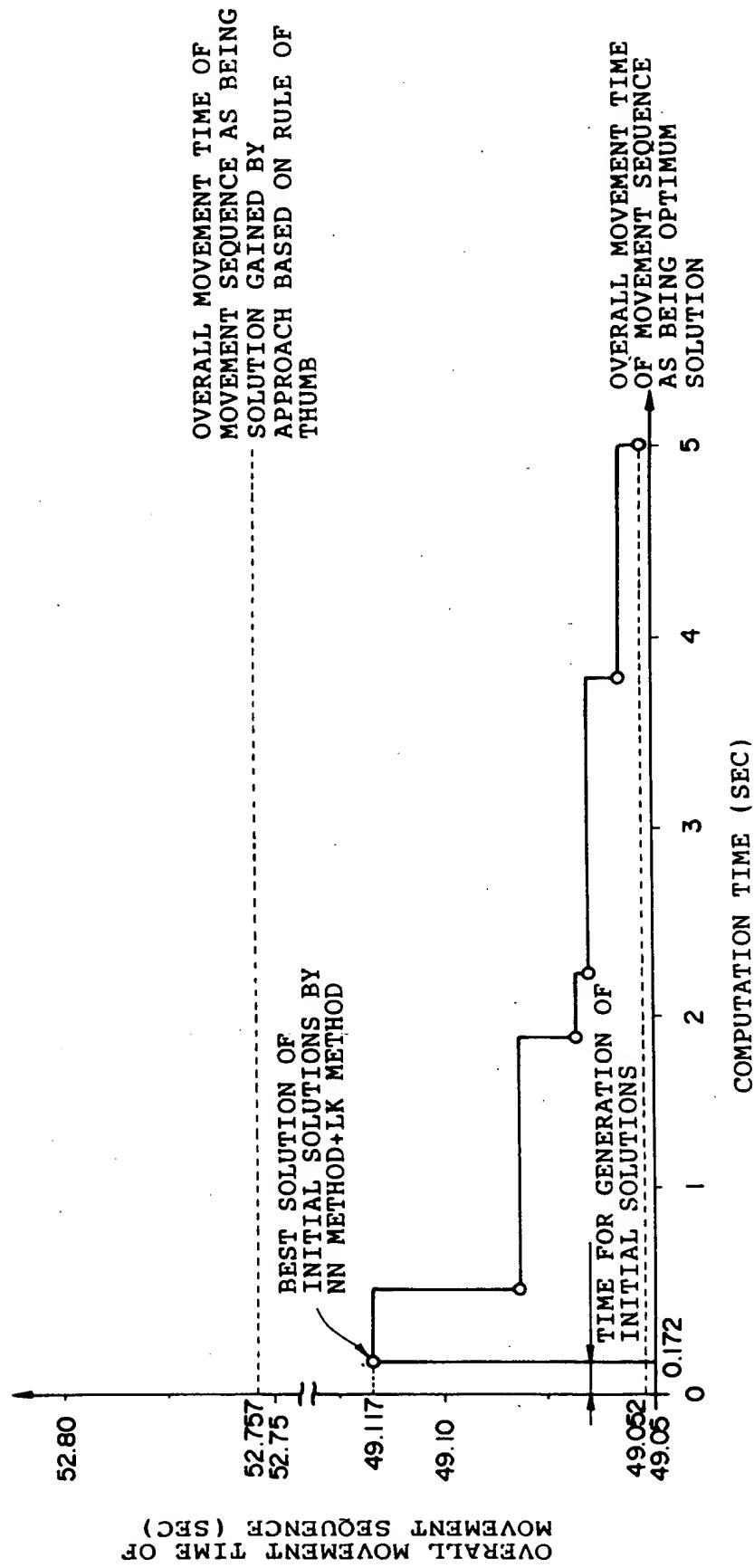


Fig. 26

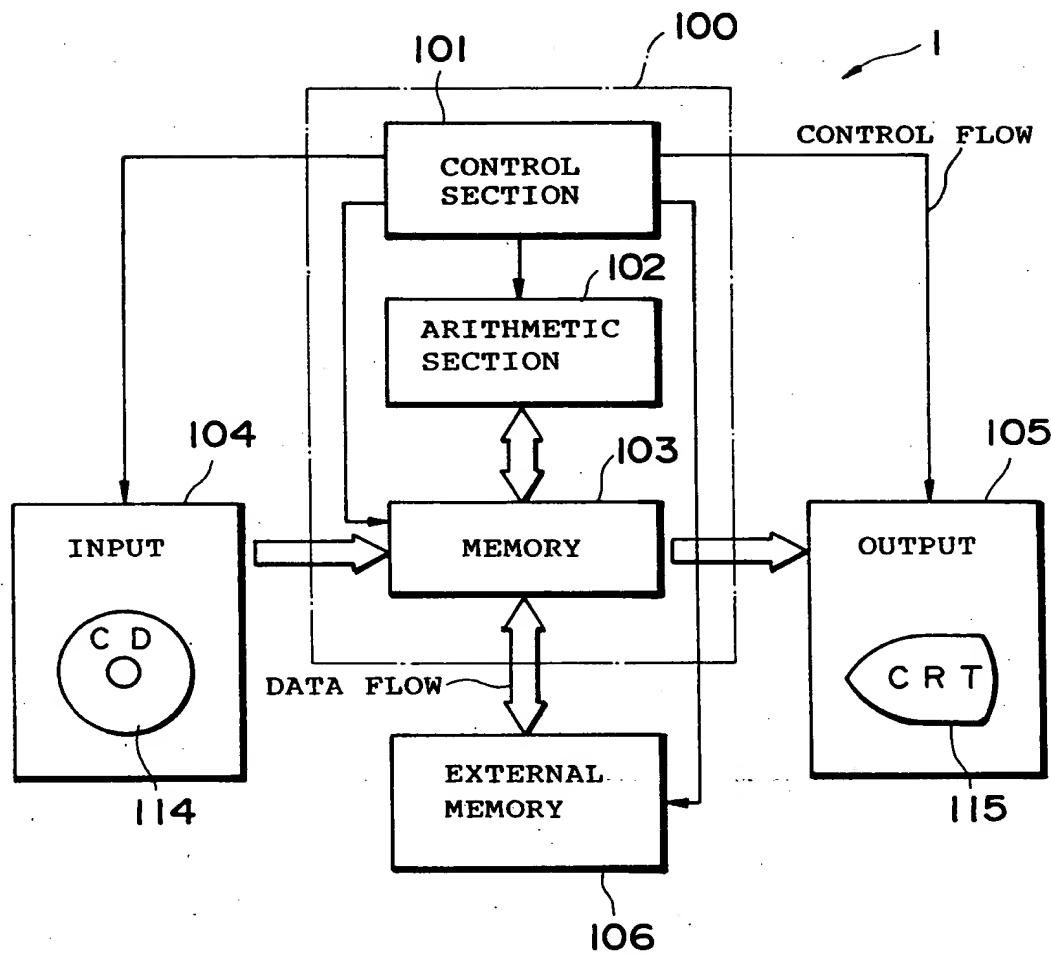


Fig. 27

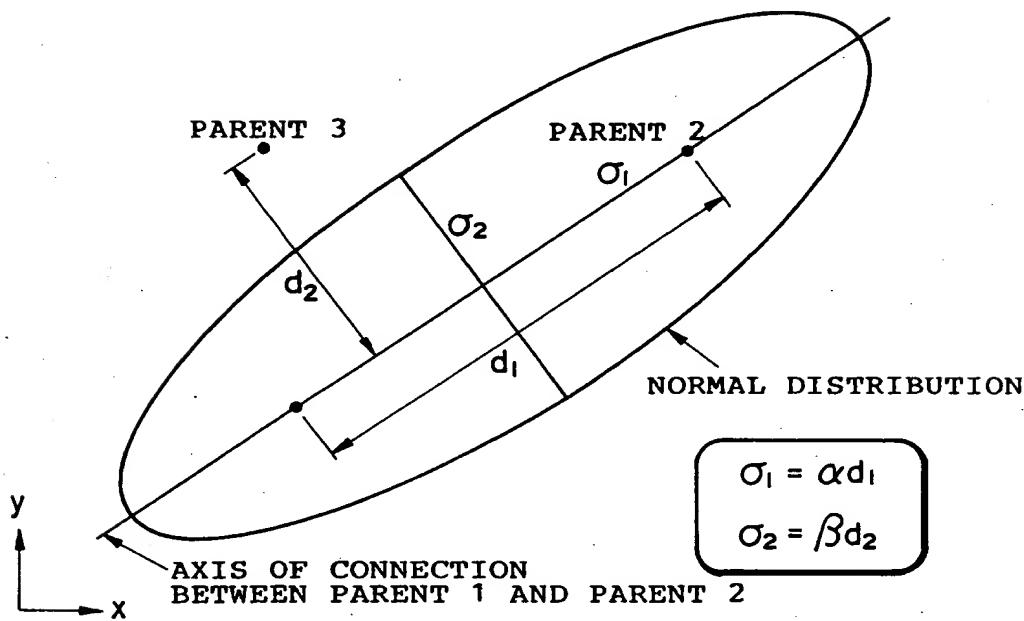
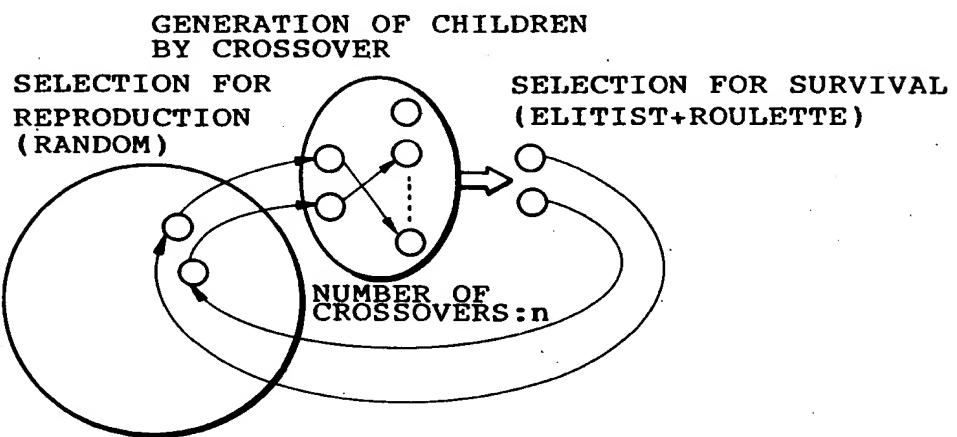


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Fig. 29

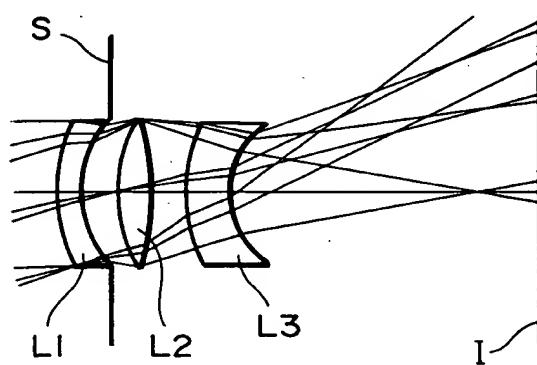
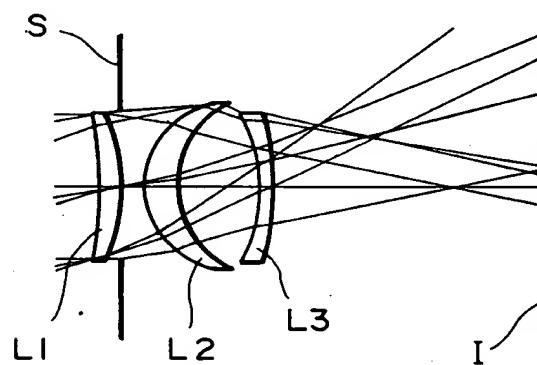


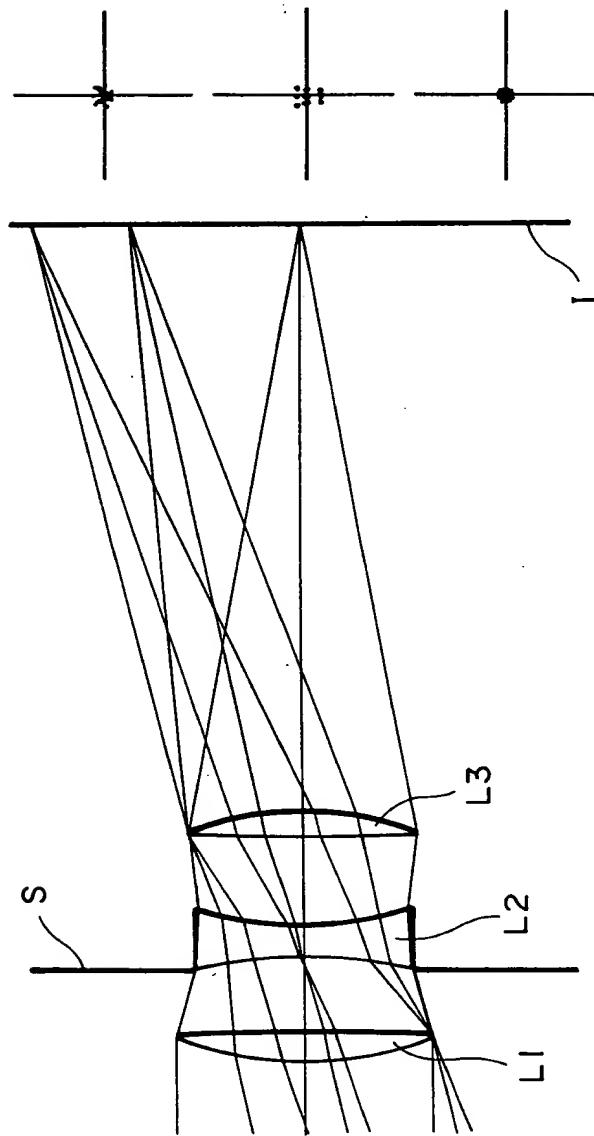
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DOCKET NO.: 061807-0137

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Fig. 32

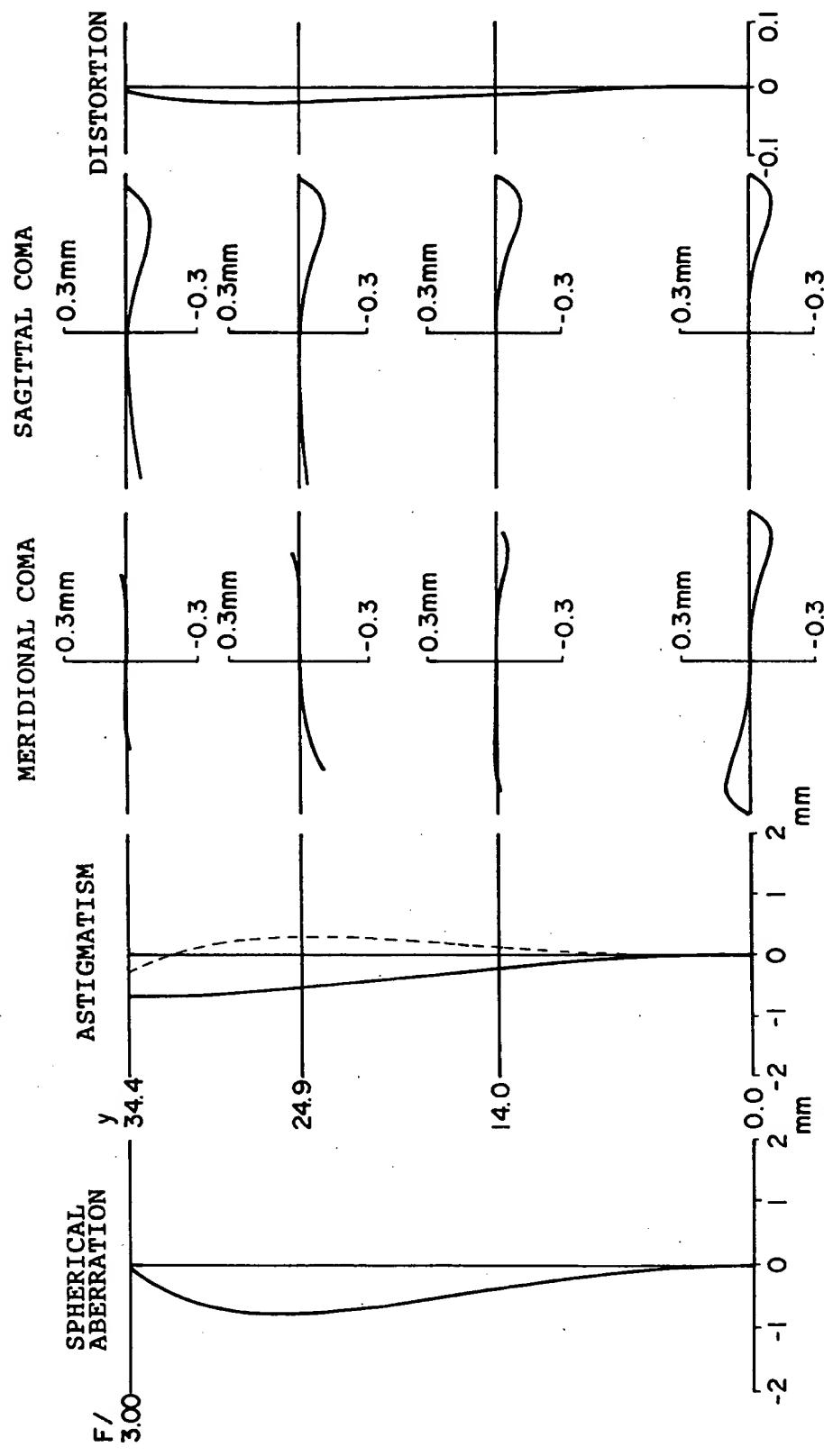


Fig. 33

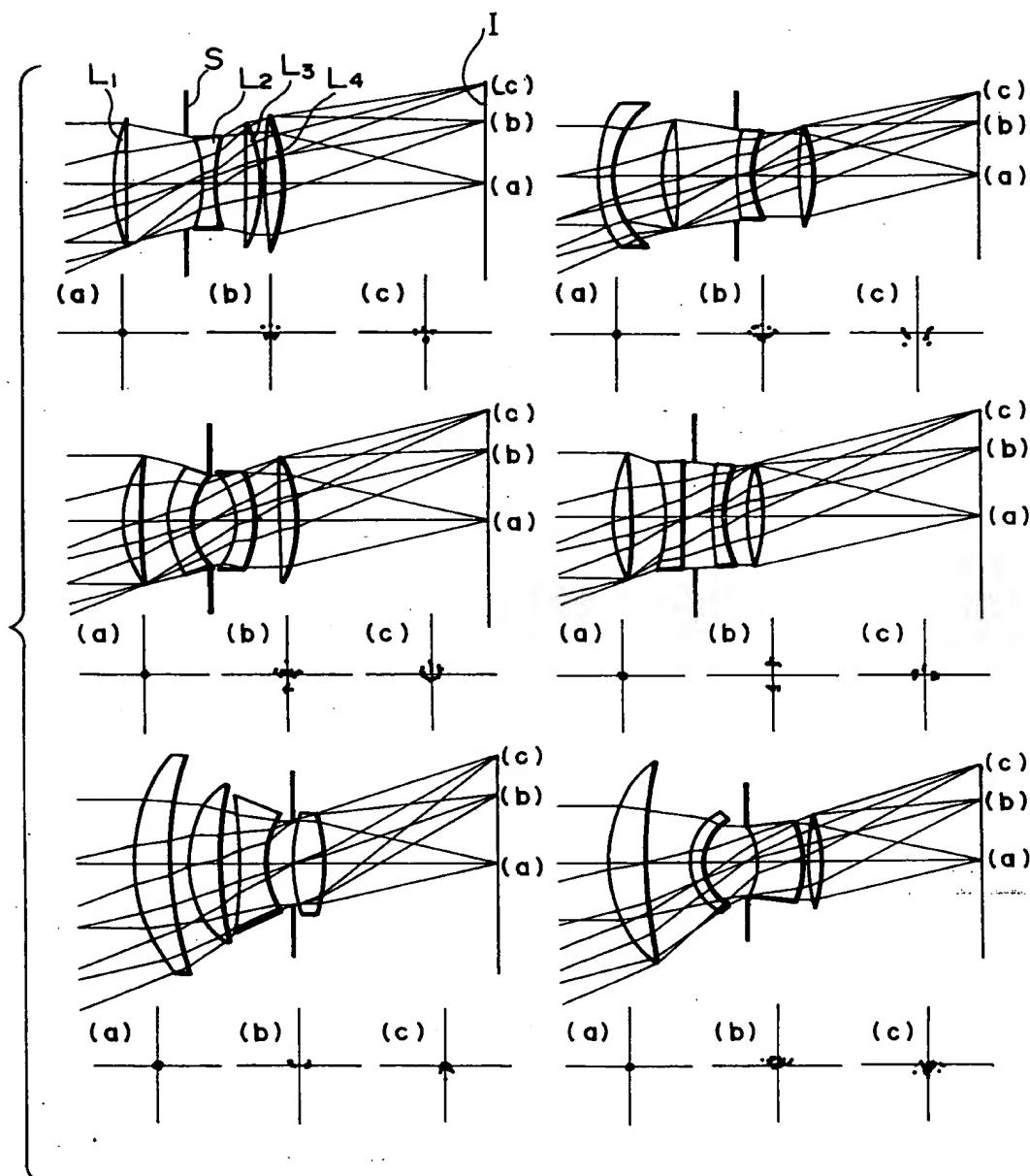
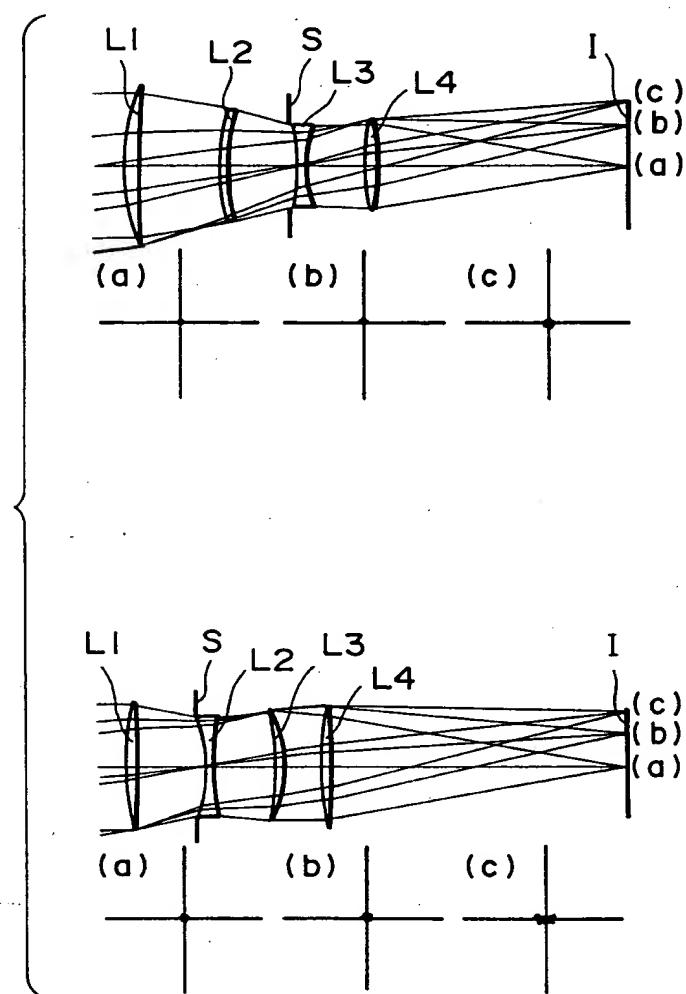


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Fig. 35

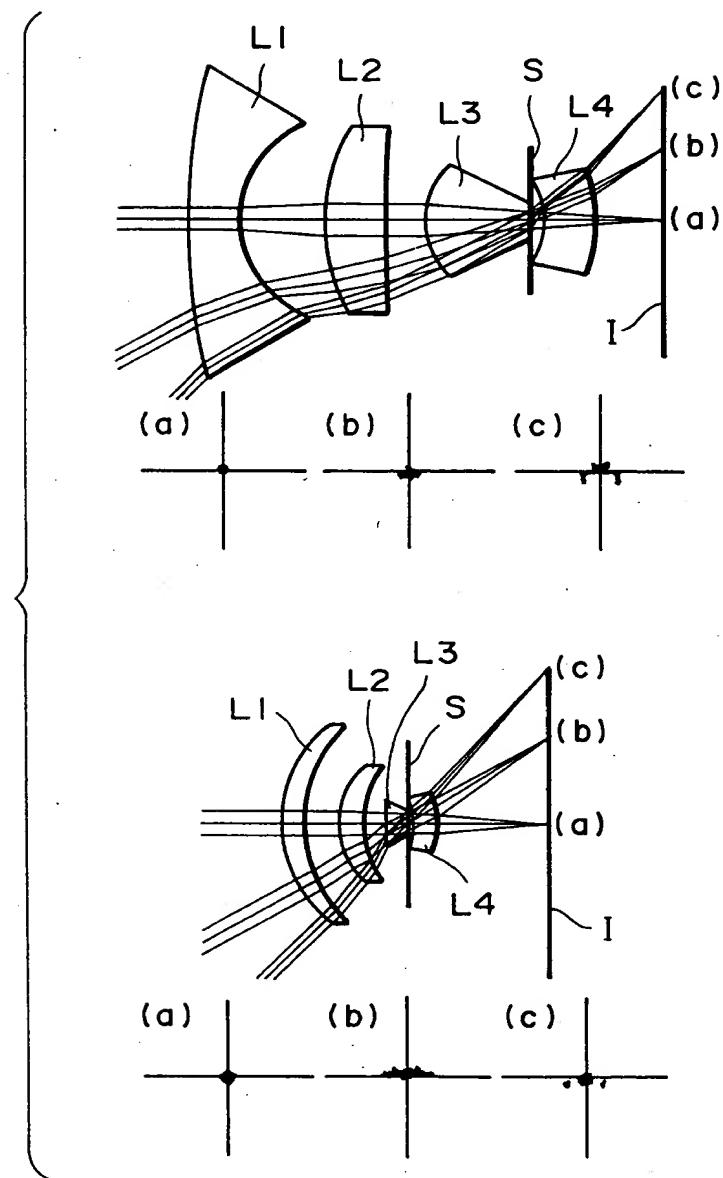
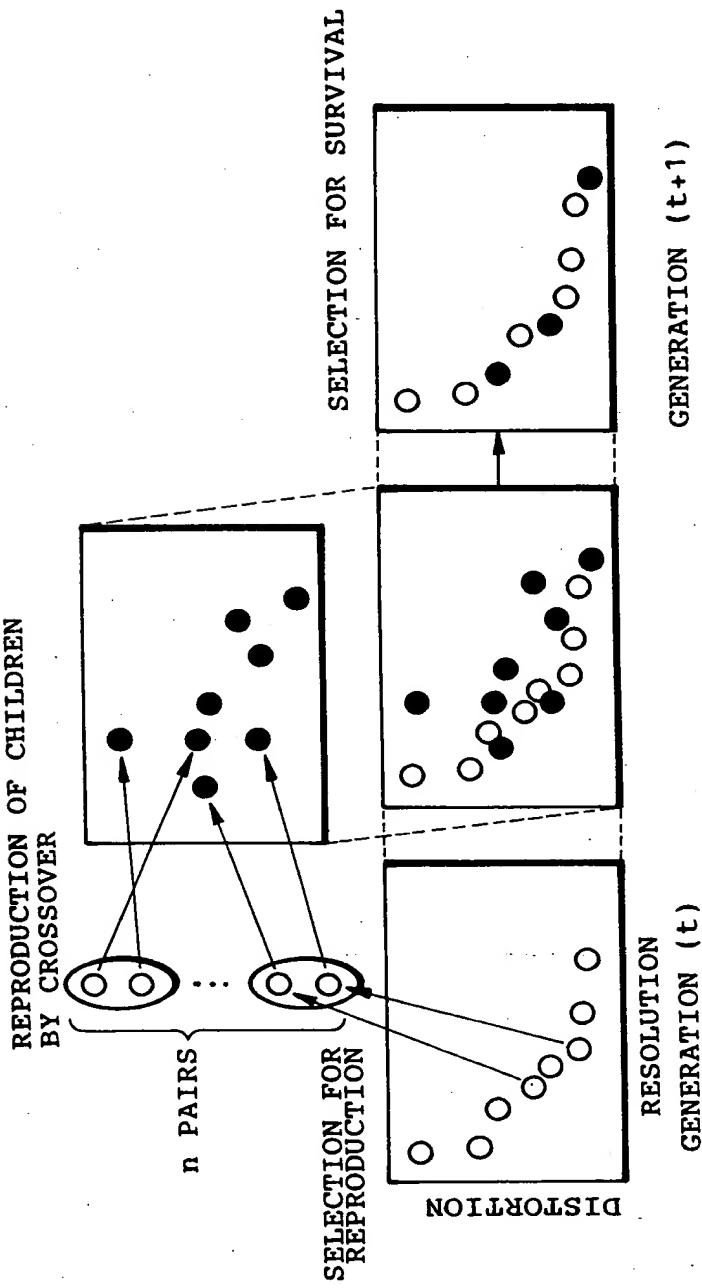


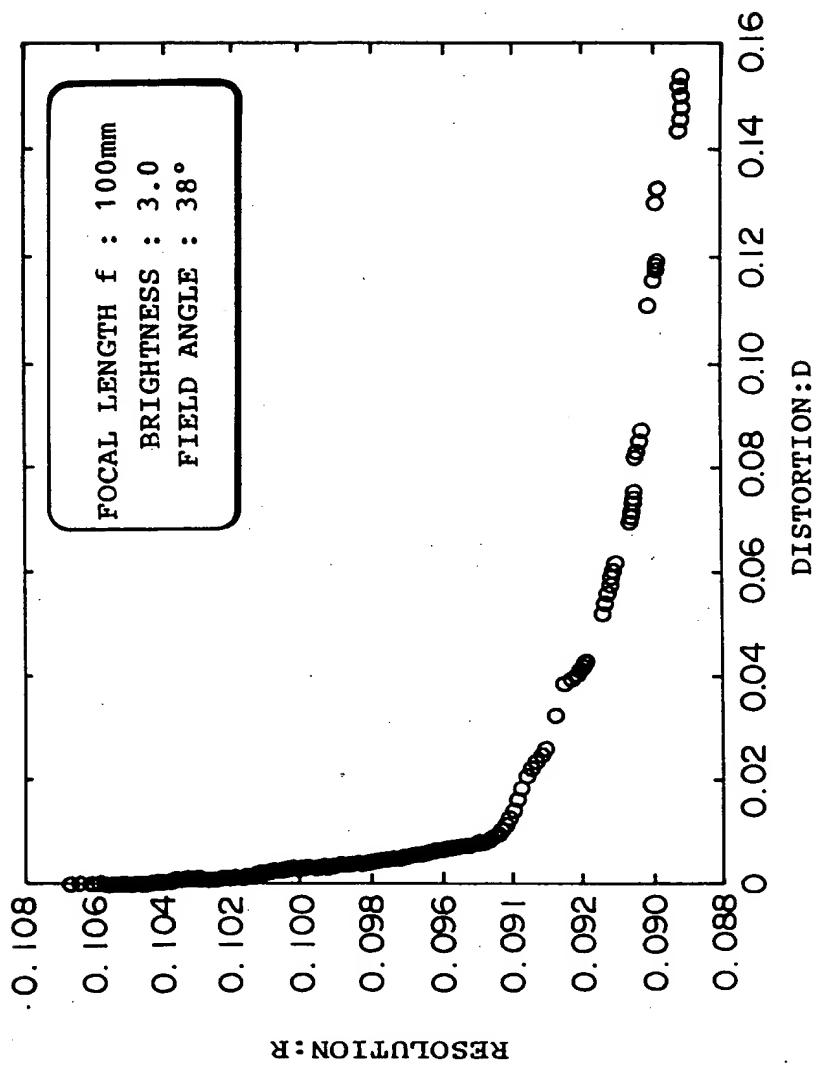
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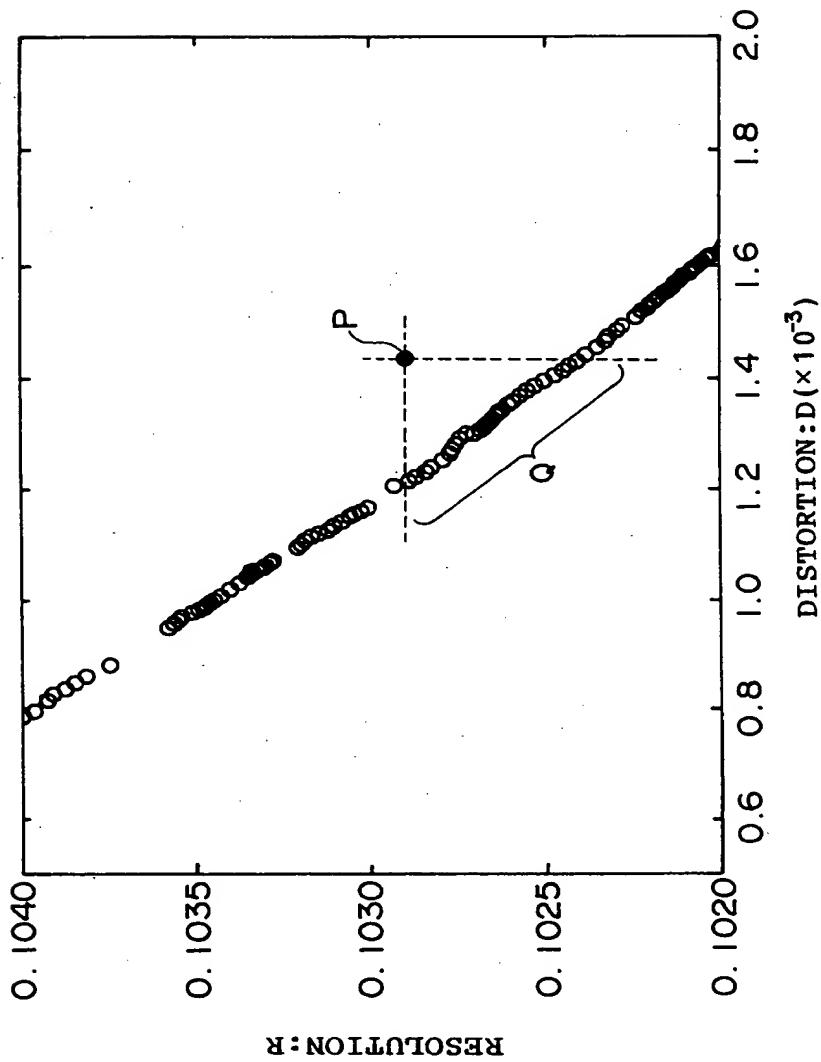
Fig. 37



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DOCKET NO.: 061807-0137

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Fig. 39

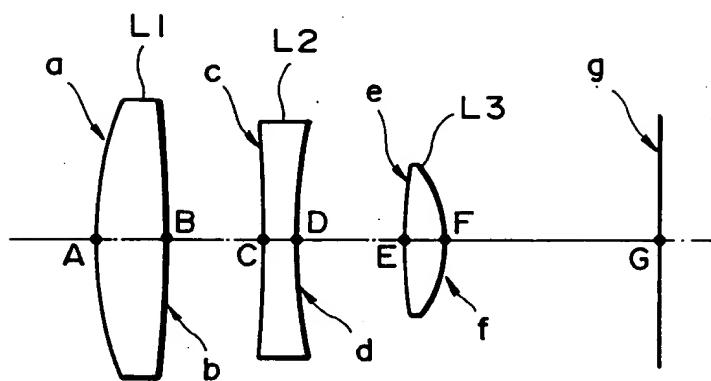


Fig. 41

GENE
REPRESENTATION:

a	b	c	d	e	d1	d2	d3	d4	d5
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Fig. 40

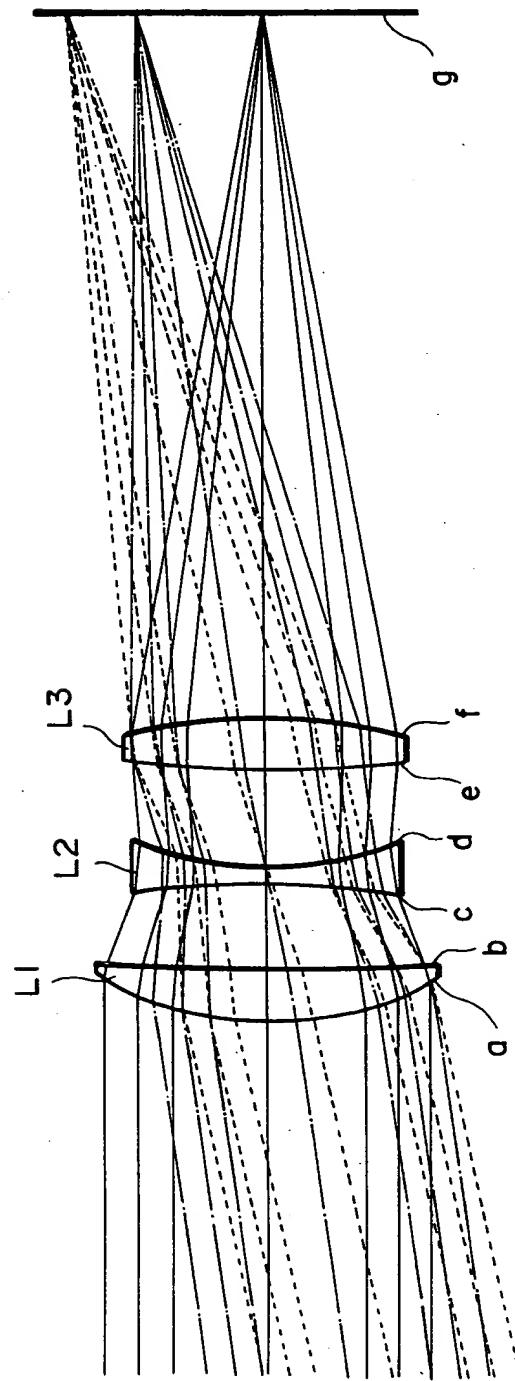
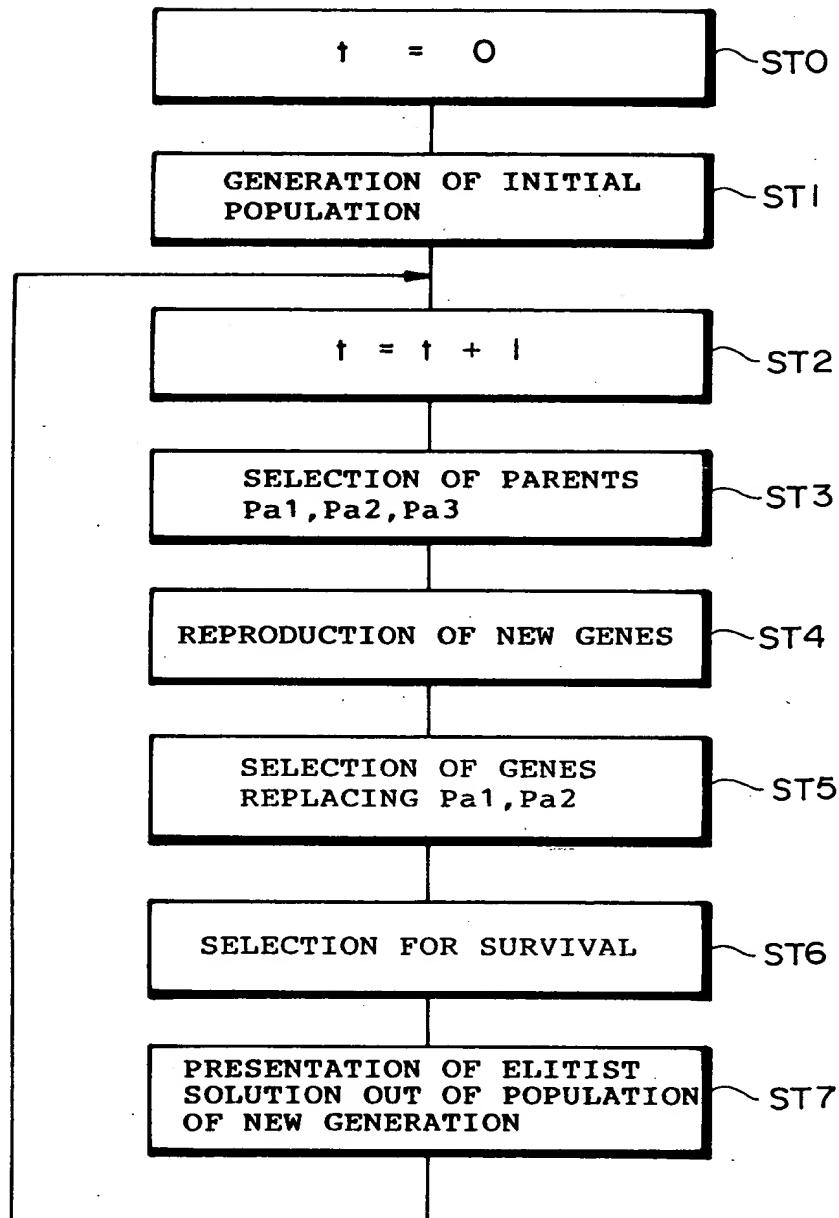


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DOCKET NO.: 061807-0137

Fig. 43

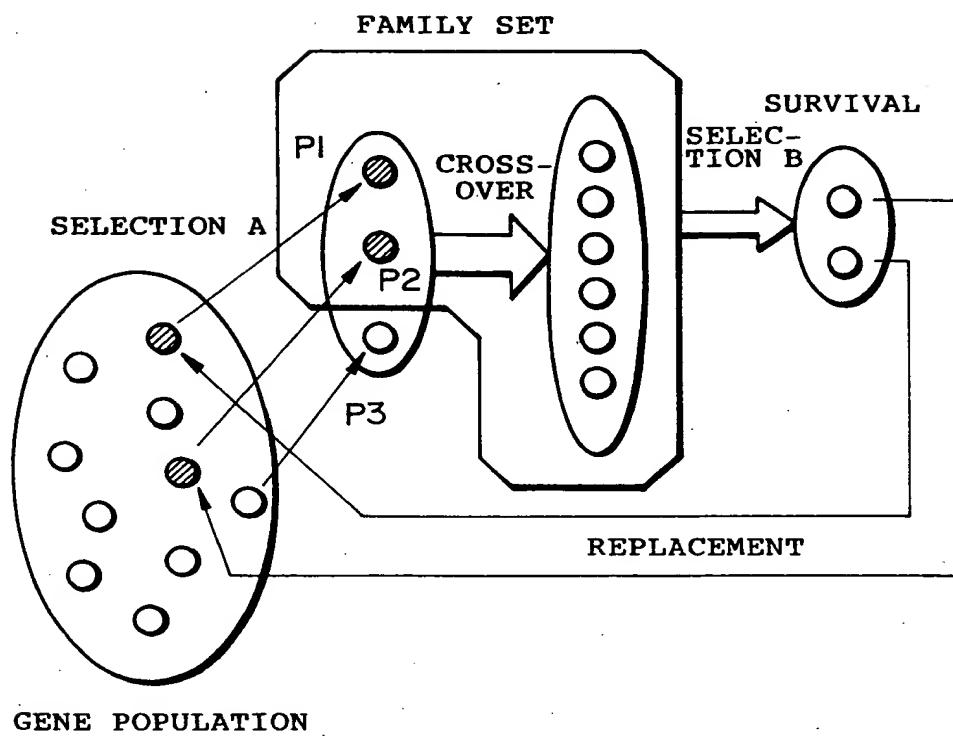
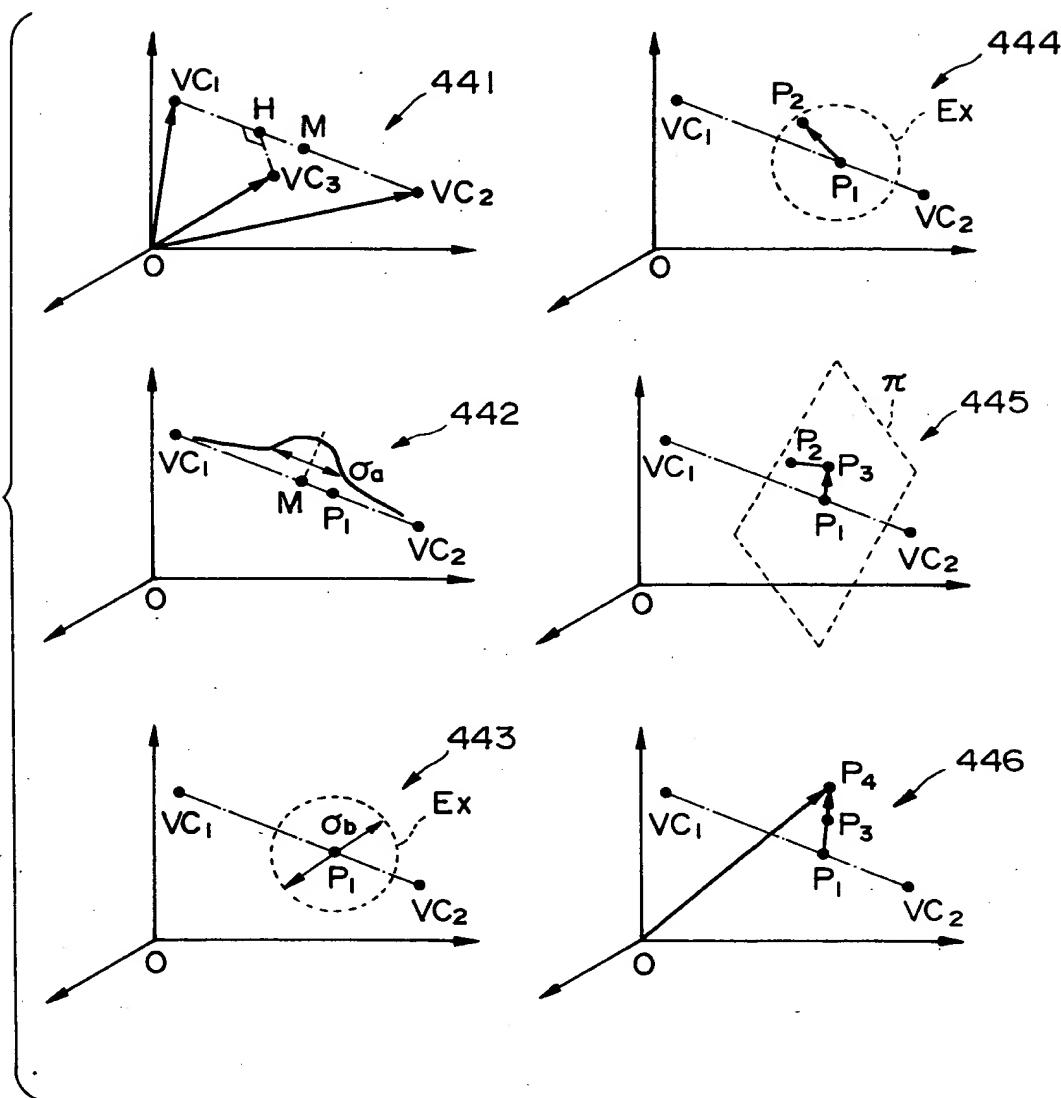
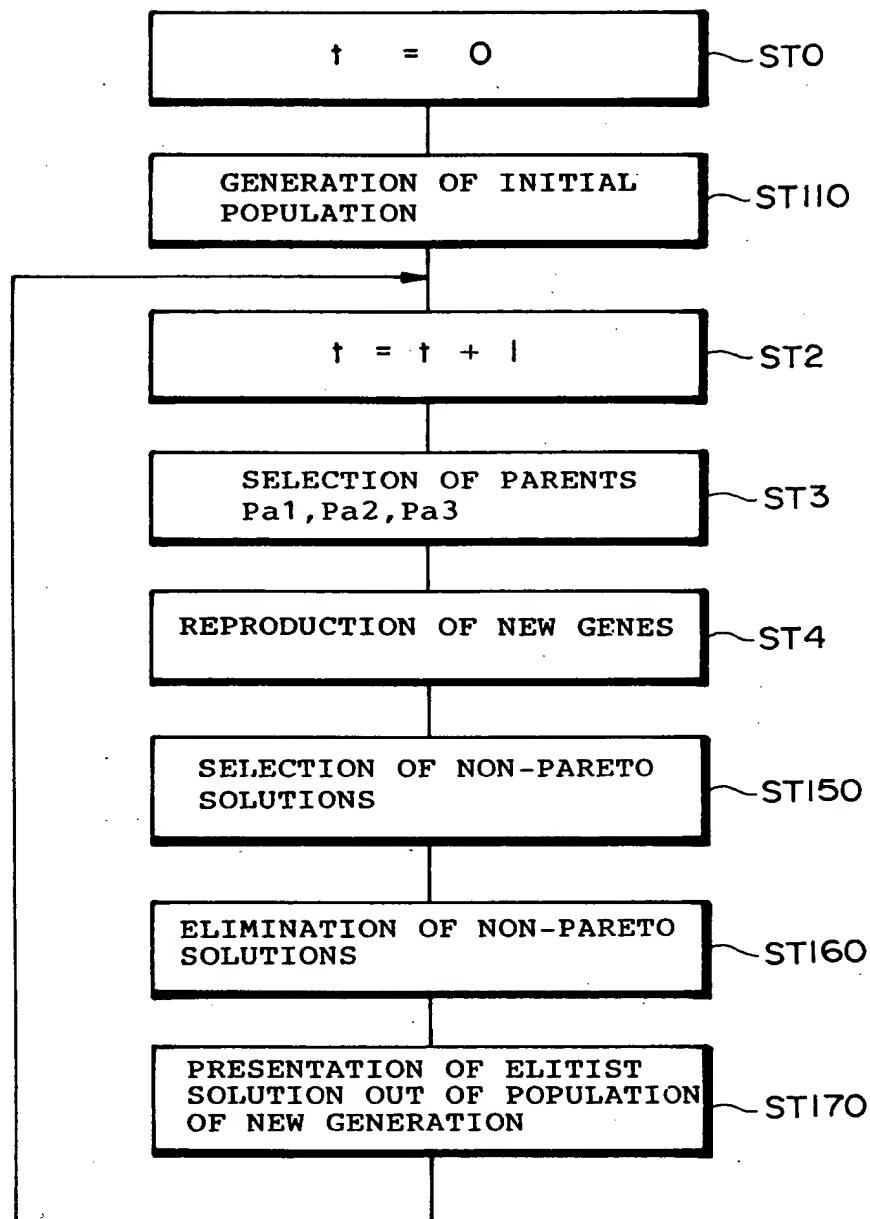


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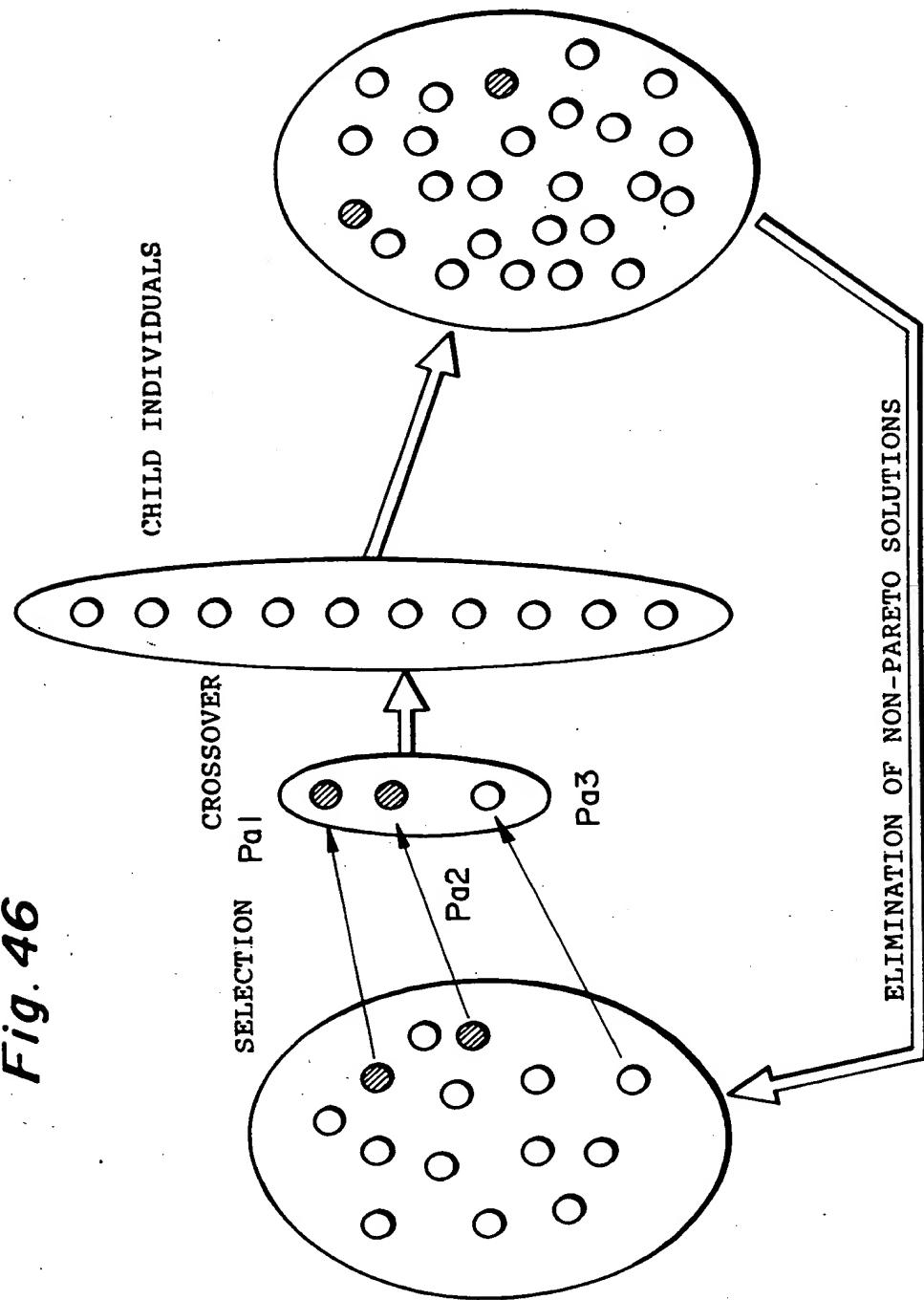
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DOCKET NO.: 061807-0137

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DOCKET NO.: 061807-0137

Fig. 47

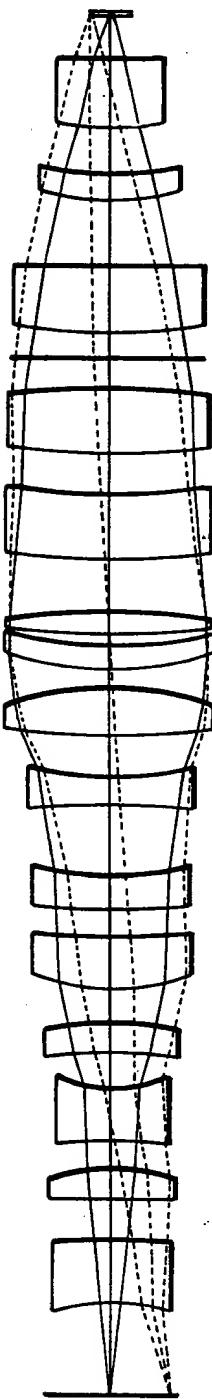
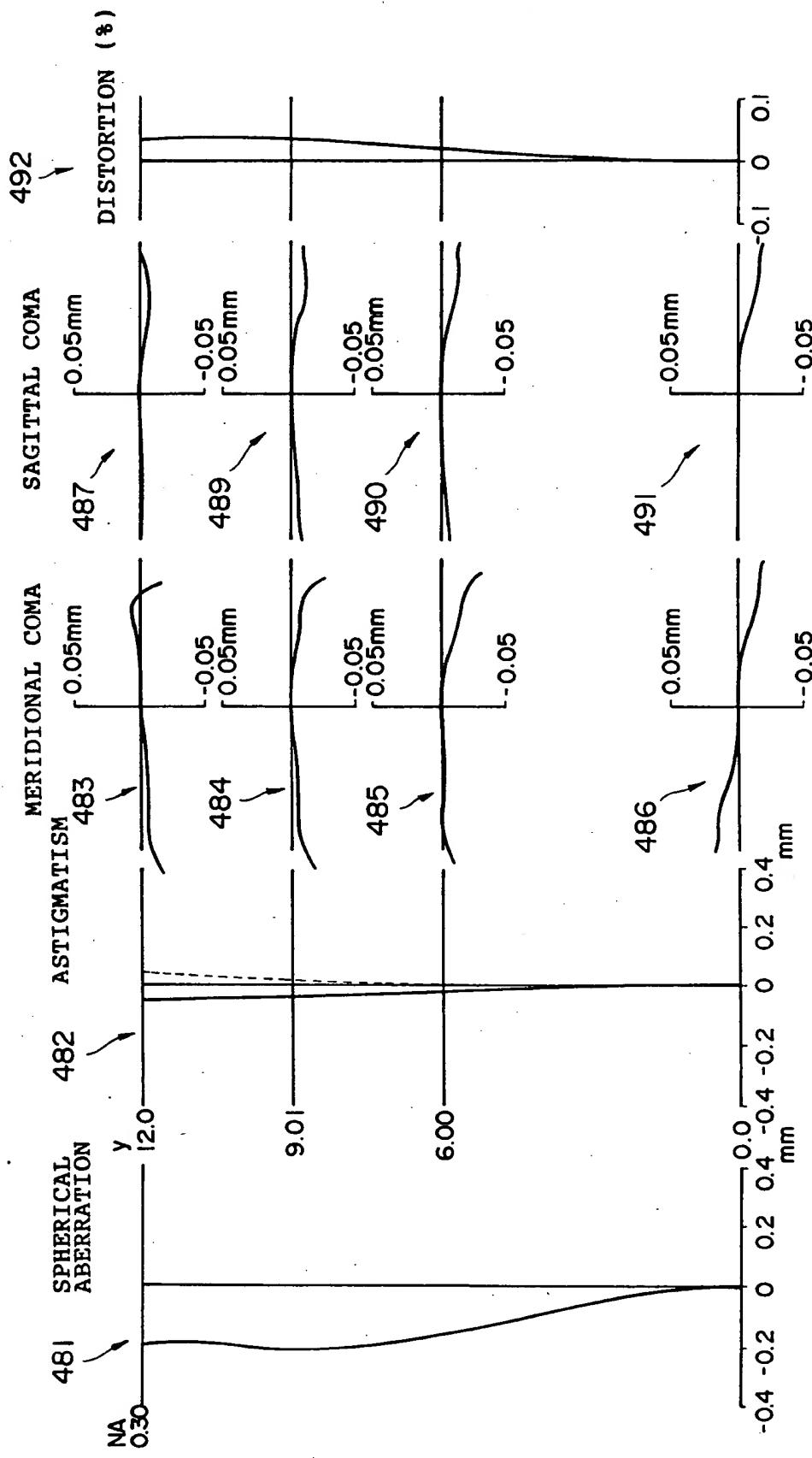


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Fig. 49

